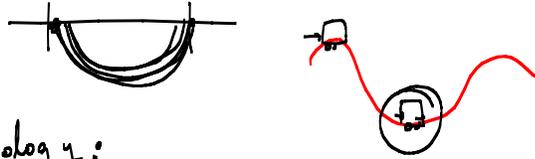


Chp 14: Periodic Motion ~ Oscillations

Seasons 8



Some terminology:

Period: The time to complete one full cycle

Amplitude: max. mag. of displacement from equil. posn.

0-point: = stable eq. position

Frequency: # of cycles per unit time $\Rightarrow f = \frac{1}{T} = s^{-1}$
 \Rightarrow Hz

Hz \Rightarrow Heinrich Hertz (1850 ~)

Ang. freq: $\frac{2\pi}{T} = \omega$

Simple Harmonic Motion:

$F = (\text{const}) x$

$F = -k x$ constant

$f_x = m a_x = m \frac{d^2 x}{dt^2} = -k x$

$\frac{d^2 x}{dt^2} = -\frac{k}{m} x$

$\frac{d^2 \theta}{dt^2} = -\frac{g}{L} \theta$

$A \cos(x) + B \sin(x)$

$\frac{d^2 x}{dt^2} + \left(\frac{k}{m}\right) x = 0$

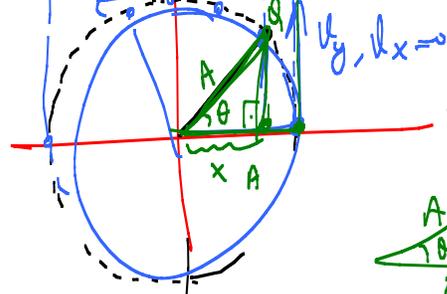
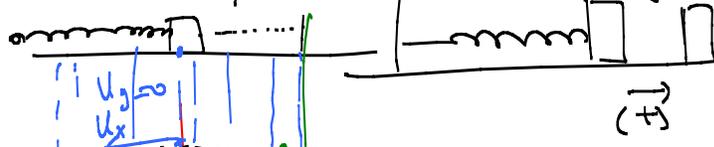
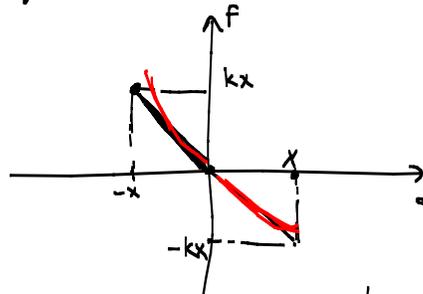
- $\cos(\omega t)$
- $-a \sin(\omega t)$
- $-a^2 \cos(\omega t)$

$e^{ix} \Rightarrow \cos x + i \sin x$ $A \cos\left(\sqrt{\frac{k}{m}} t\right)$

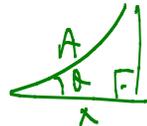
$$\frac{dx}{dt} = 3 \Rightarrow \int dx = \int 3 dt$$

$$x = 3t + C$$

Analogy with Circular Motion



$$x = A \cos \theta$$



$$f = \frac{mv^2}{r} = m\omega^2 r = ma$$

$$a_a = \omega^2 A$$

$$a_a \rightarrow a_x$$

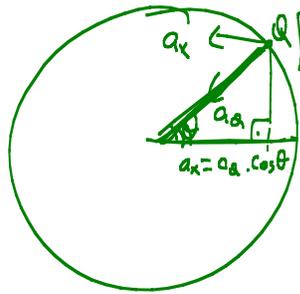
$$a_x = -a_a \cos \theta$$

$$a_x = -\omega^2 A \cos \theta$$

$$a_x = -\omega^2 x$$

$$F = -kx$$

$$F = ma_x$$



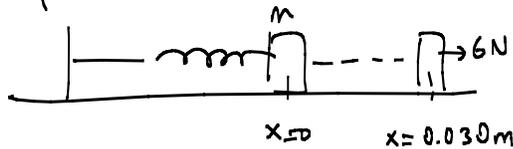
$$F = kx = ma_x = m\omega^2 x$$

$$\omega^2 = \frac{k}{m} \Rightarrow \omega = \sqrt{\frac{k}{m}}$$

$$\omega = 2\pi f \Rightarrow f = \frac{1}{2\pi} \omega = \frac{1}{2\pi} \sqrt{\frac{k}{m}} = f$$

$$f = \frac{1}{T} \Rightarrow \omega = 2\pi f$$

Example



$$F = -kx$$

$$k = \frac{6}{0.03} = 200 \text{ N/m} \quad m = 0.50 \text{ kg}$$

a)

b) $\omega = ?$, $f = ?$, $T = ?$

$$\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{200}{0.5}} = \sqrt{400} = 20$$

$$\omega = 20 \text{ rad/s}$$

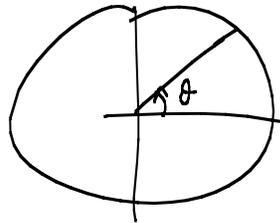
$$f = \frac{\omega}{2\pi} = \frac{20 \text{ rad/s}}{2\pi \text{ rad/cycle}} = \frac{20}{2\pi} \text{ cyc/sec} \stackrel{\text{Hz}}{=} 3.2 \text{ Hz}$$

$$T = \frac{1}{f} = \frac{1}{3.2 \text{ cyc/sec}} = 0.31 \text{ s}$$

$$x = A \cos(\theta)$$

$$\theta(t) = \omega t + \theta_0$$

$$x(t) = A \cos(\omega t + \theta_0)$$



$$x(t) = A \cos[\omega t + \phi]$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$\frac{d^2x}{dt^2} + \frac{k}{m}x = 0$$

$$u(t) = \frac{dx}{dt}$$

$$-\frac{k}{m}x + \frac{k}{m}x = 0$$

$$u = \frac{d}{dt} (A \cos(\omega t + \phi)) = -A\omega \sin(\omega t + \phi)$$

$$\boxed{u = -A\omega \sin(\omega t + \phi)} \quad \text{vel. in SHM}$$

$$a = \frac{du}{dt} = \frac{d^2x}{dt^2} \Rightarrow \frac{d}{dt} [-A\omega \sin(\omega t + \phi)]$$

$$a_x = -A\omega^2 \cos(\omega t + \phi)$$

$$\boxed{x = A \cos(\omega t + \phi)}$$

$$\boxed{a_x = -A\omega^2 \cos(\omega t + \phi)}$$

acc. in SHM

$$a = -\omega^2 x = -\omega^2 A \cos(\omega t + \phi)$$

$$\frac{d^2x}{dt^2} = \frac{k}{m}x$$

$$\boxed{u_{0x}, x_0}$$

$$\omega = \frac{2\pi}{T}$$

$$\boxed{u(t) = -A\omega \sin(\omega t + \phi)}$$

$$\boxed{x(t) = A \cos(\omega t + \phi)}$$

$$u(t=0) = u_0 = -A\omega \sin \phi$$

$$x(t=0) = x_0 = A \cos \phi$$

$$\frac{u_0}{x_0} = \frac{-A\omega \sin \phi}{A \cos \phi} = -\omega \tan \phi = \frac{u_0}{x_0}$$

$$\boxed{\phi = \arctan\left(-\frac{u_0}{\omega x_0}\right)}$$

$$\tan \phi = -\frac{u_0}{\omega x_0}$$

$$v_0^2 = A^2 \omega^2 \sin^2 \phi$$

$$+ \omega^2 x_0^2 = A^2 \omega^2 \cos^2 \phi$$

$$v_0^2 + \omega^2 x_0^2 = A^2 \omega^2 (\sin^2 \phi + \cos^2 \phi)$$

$$A = \sqrt{\frac{v_0^2 + \omega^2 x_0^2}{\omega^2}}$$

$$\int f \cdot dx = U(x) \quad \left[-\frac{dU}{dx} = f \right]$$

$$\int kx \cdot dx$$

En. in SHM

$$E = \frac{1}{2} m v_x^2 + \frac{1}{2} k x^2 = \text{constant} = \frac{1}{2} k A^2$$

$$v_x=0 \Rightarrow x=A \Rightarrow E = \frac{1}{2} k A^2 = \text{constant}$$

Putting $v_x, x \Rightarrow E = \frac{1}{2} m \left[-A \omega \sin(\omega t + \phi) \right]^2 + \frac{1}{2} k \left[A \cos(\omega t + \phi) \right]^2$

$$= \frac{1}{2} m A^2 \omega^2 \sin^2(\omega t + \phi) + \frac{1}{2} k A^2 \cos^2(\omega t + \phi)$$

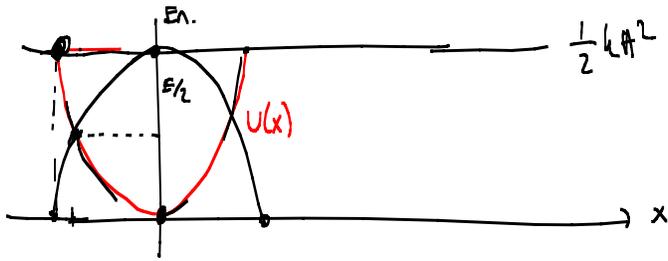
$$= \frac{1}{2} k A^2 \sin^2(\omega t + \phi) + \frac{1}{2} k A^2 \cos^2(\omega t + \phi) = \frac{1}{2} k A^2$$

$$\frac{1}{2} k x^2 + \frac{1}{2} m v^2 = \frac{1}{2} k A^2$$

$$\frac{m v^2}{m} = k A^2 - k x^2 = \frac{k}{m} (A^2 - x^2)$$

$$v^2 = \frac{k}{m} (A^2 - x^2)$$

$$v = \sqrt{\frac{k}{m} (A^2 - x^2)}$$

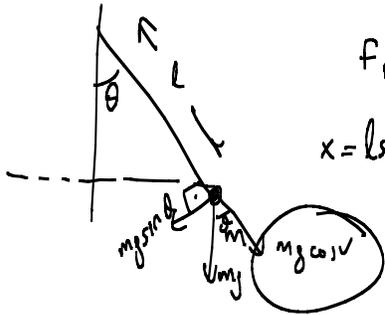


$$\frac{1}{2} m v^2 = KE$$

$$\frac{1}{2} k x^2 = U(x)$$

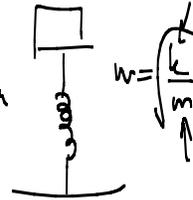
The Simple Pendulum :

$$KE + U(x) = \text{const}$$



$$F_{\theta} = -mg \sin \theta = ma$$

$$x = l \sin \theta$$



$$a = \frac{d^2 x}{dt^2}, \quad \alpha = \frac{d^2 \theta}{dt^2}$$

$$-mg \sin \theta = m a l = ml \frac{d^2 \theta}{dt^2}$$

$$-\frac{g \sin \theta}{l} = \frac{d^2 \theta}{dt^2} \Rightarrow \frac{d^2 \theta}{dt^2} = -\frac{g}{l} \theta$$

~~$\sin x = x - \frac{x^3}{6} + \frac{x^5}{120}$~~

$$\frac{d^2 x}{dt^2} = -\frac{k}{m} x$$

$$\omega = \sqrt{\frac{g}{L}} \Rightarrow T = \frac{2\pi}{\omega} = \boxed{\frac{2\pi}{\sqrt{g/L}}}$$