

Chp 5 - App. of Newton's Laws

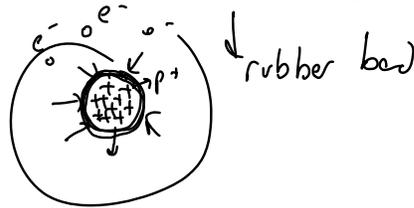
Types of forces: $F \propto \frac{1}{r^2}$

1) • Grav. force (universal) valid on all scales (galaxies, earth, small particles electrons)

• Force friction, fluid resistance, spring force, etc complicated in nature. $\downarrow kx, \rho v^2$

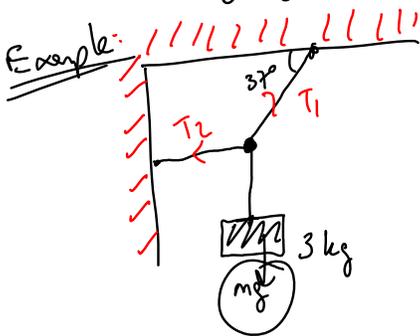
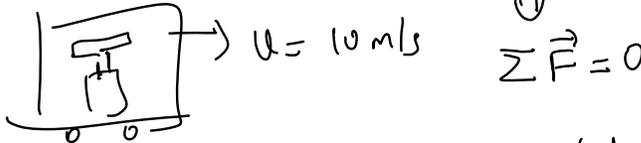
2) • Electromagnetic force $\propto \frac{1}{r^2}$

3) • Weak force (nuclear decays) : ↑ Strong force (force which holds atoms)



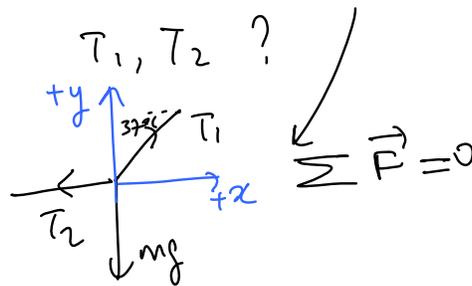
I) Equilibrium (of a system)

The system has total $\vec{a} = 0$. (not necessarily $\vec{v} = 0$)



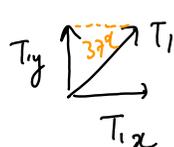
FBD (Free body diagram)

⇒ system is in equilibrium



Equil. cond:

$$\left. \begin{aligned} \sum F_x &= 0 \\ \sum F_y &= 0 \end{aligned} \right\}$$



$$\begin{aligned} T_{1y} &= T_1 \cdot \sin 37^\circ \\ T_{1x} &= T_1 \cdot \cos 37^\circ \end{aligned}$$

$$\sum F_x = 0 \Rightarrow T_1 \cos 37^\circ - T_2 = 0 \quad (1) \quad \sum F_y = 0 \Rightarrow T_1 \sin 37^\circ - mg = 0 \quad (2)$$

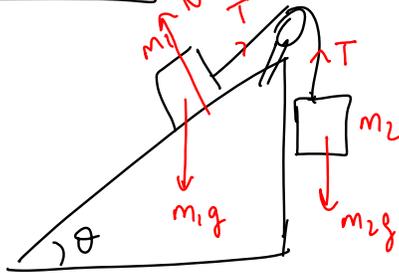
(1) $T_1 \frac{4}{5} = T_2 \Rightarrow (2) \Rightarrow T_1 \frac{3}{5} = 3 \times 10$ ↓ $T_1 \sin \theta = m_2 g$

$\Rightarrow 5 \times \frac{4}{5} = T_2$

$T_1 = 50 \text{ N}$

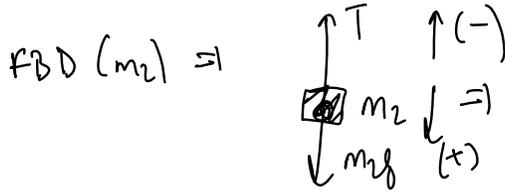
$T_2 = 40 \text{ N}$

Example



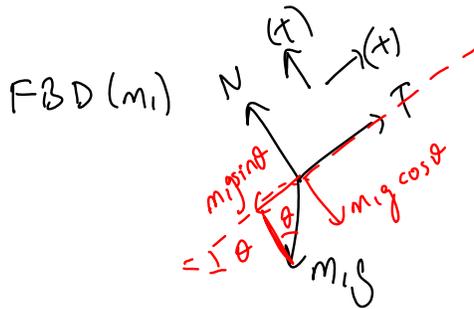
If the sys. is in equl.

then what is $\frac{m_1}{m_2} = ?$



$\sum \vec{F} = 0$
 $m_2 g - T = 0$

$T = m_2 g$



$\sum \vec{F} = 0$
 $\sum F_{\perp} = N - m_1 g \cos \theta = 0$
 $\sum F_{\parallel} = T - m_1 g \sin \theta = 0$

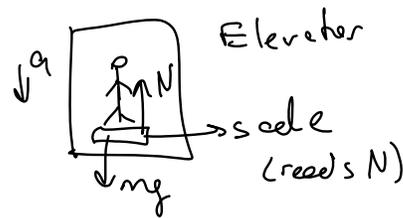
$m_2 g - m_1 g \sin \theta = 0 \Rightarrow$

$\frac{m_1}{m_2} = \frac{1}{\sin \theta}$

II) Dynamics (a non-zero \vec{a})

$\sum \vec{F} = \sum m \vec{a}$

$mg - N = ma$

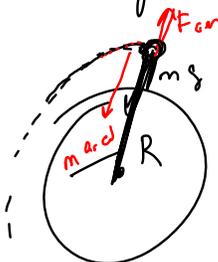


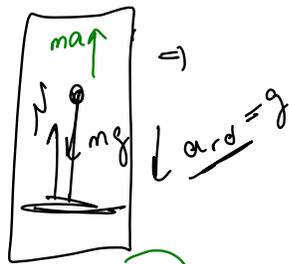
$N = mg - ma \Rightarrow$ Apparent weight



Astronauts on a satellite

they feel weightless





$$mg - ma = 0$$

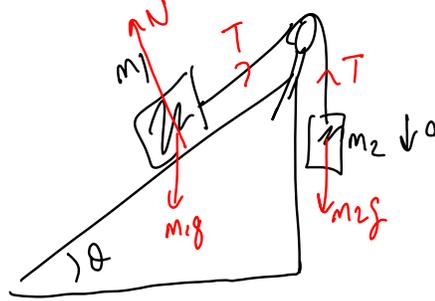
$$mg - N = ma$$

$$N = 0$$

$$\sum F = \sum ma$$

$$\sum (F - ma) = 0 \Rightarrow mg - N - ma = 0$$

• Example

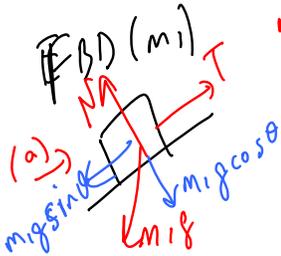


$$\frac{m_1}{m_2} = ?$$

FBD (m_2)

$$\sum F = \sum ma$$

$$m_2g - T = m_2a \quad (1)$$



$$\sum \vec{F} = ma$$

$$\sum F_{\perp} = 0 ; \sum F_{\parallel} = m_1 a$$

$$N - m_1 g \cos \theta = 0 ; T - m_1 g \sin \theta = m_1 a$$

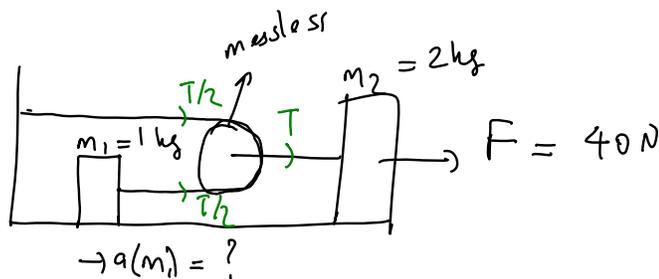
$$T = m_1 (a + g \sin \theta)$$

$$m_2 g - m_1 (a + g \sin \theta) = m_2 a$$

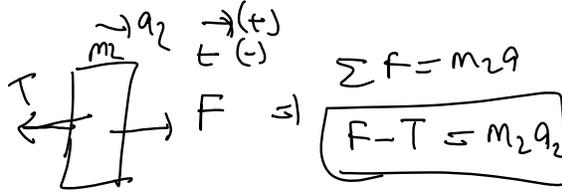
$$m_2 (g - a) = m_1 (a + g \sin \theta)$$

$$\frac{m_1}{m_2} = \frac{g - a}{a + g \sin \theta}$$

Example



FBD(m₂)



FBD(m₁)



$$\Sigma f = m_1 a_1$$

$$T' = m_1 a_1$$

$$\Downarrow$$

$$\frac{T}{2} = m_1 a_1 = m_1 2a_2$$

$$a_1 = 2a_2$$

$$a_1 = 2a_2$$

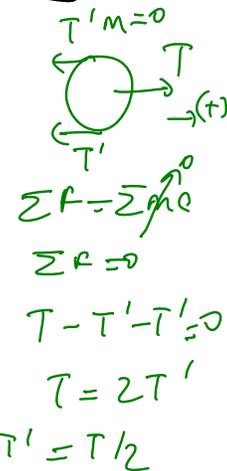
$$F - T = m_2 a_2$$

$$\left(\frac{T}{2} \right) = 2m_1 a_2 \Rightarrow T = 4m_1 a_2$$

$$F - 4m_1 a_2 = m_2 a_2 \Rightarrow F = a_2 [m_2 + 4m_1]$$

$$a_2 = \frac{F}{m_2 + 4m_1} = \frac{40}{2 + 4} = \frac{40}{6} = \frac{20}{3} \approx 6.7$$

$$a_1 \approx 13.4 \text{ m/s}^2 = 2a_2$$

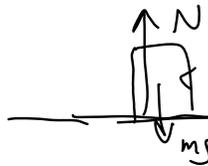
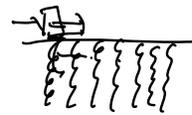


$$T' = T/2$$

Friction

Kinetic friction: $F_k = \mu_k N$

Static friction $\Rightarrow F_s \leq \mu_s N$

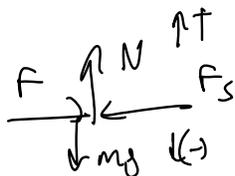


if it is not moving

not pushing it $F_s = 0$

defined as

$\mu_s \Rightarrow$ max amount of F so that m will not move



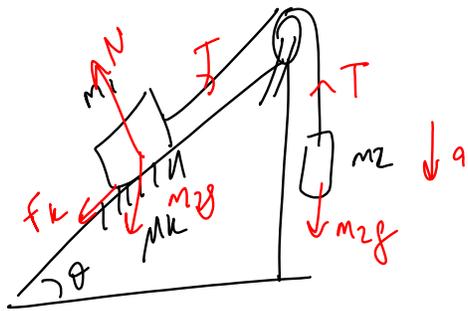
$$N - mg = 0$$

$$F - F_s = 0$$

$$\Rightarrow N = mg$$

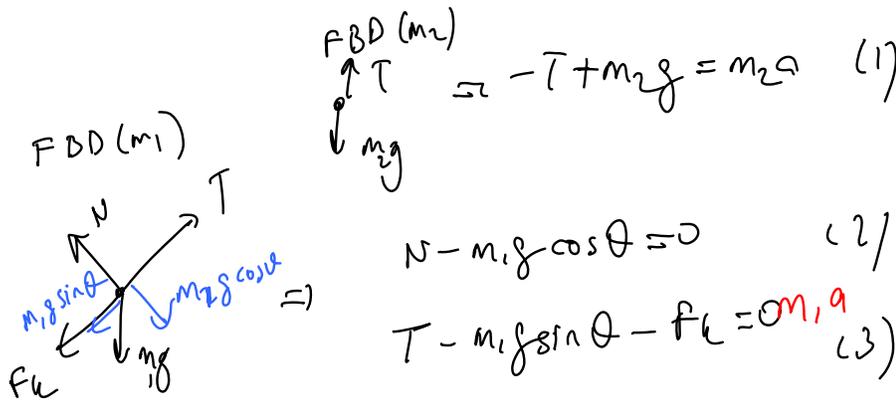
$$F = F_s = \mu_s N = \mu_s mg$$

$$\boxed{\mu_s = \frac{F}{mg}}$$



$$\frac{m_1}{m_2} = ?$$

* The direction of friction is always opposite to the direction of motion!



$$\text{FBD}(m_2) \quad \uparrow T \quad \downarrow m_2 g \quad \Rightarrow \quad -T + m_2 g = m_2 a \quad (1)$$

$$N - m_1 g \cos \theta = 0 \quad (2)$$

$$T - m_1 g \sin \theta - F_k = m_1 a \quad (3)$$

$$F_k = \mu_k N \quad (4) \quad \frac{m_1}{m_2} = ?$$

$$N = m_1 g \cos \theta \Rightarrow F_k = \mu_k m_1 g \cos \theta$$

$$T = F_k + m_1 g \sin \theta = (\mu_k g \cos \theta + g \sin \theta) m_1$$

$$m_2 g - T = m_2 a$$

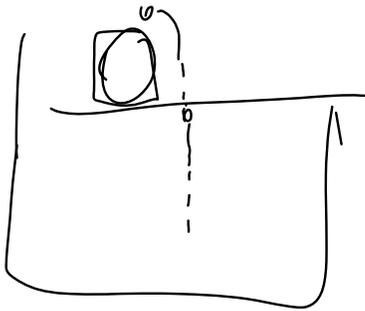
$$m_2(g - a) = T = m_1 (\mu_k g \cos \theta + g \sin \theta)$$

$$\frac{m_1}{m_2} = \frac{g - a}{\mu_k g \cos \theta + g \sin \theta + a}$$

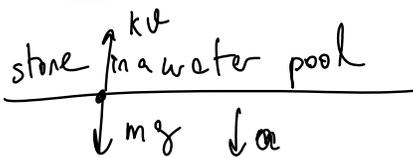
$$\boxed{\frac{m_1}{m_2} = \frac{g - a}{a + g \sin \theta}} \rightarrow \text{without friction}$$

Fluid resistance

$$F_f = kv \quad (\text{small velocity})$$



$$F_p = Dv^2 \quad (\text{large velocity})$$



$$\Sigma F = \Sigma ma$$

$$mg - kv = ma \Rightarrow mg - k \frac{dx}{dt} = m \frac{d^2x}{dt^2}$$

(Terminal speed $\Rightarrow a=0$) $vt = \text{d term}$

$$mg - kv_t = 0 \Rightarrow vt = \frac{mg}{k}$$

$$mg = kv_t$$

$$mg - kv = ma \Rightarrow mg - kv = m \frac{dv}{dt}$$

$$kv_t - kv = m \frac{dv}{dt} \Rightarrow \frac{k(v_t - v) dt = m dv}{k}$$

$$\int_0^v \frac{dv'}{v_t - v'} = -\frac{k}{m} \int_0^t dt' \quad \downarrow \frac{dv}{v_t - v} = -\frac{k}{m} dt$$

$$x = (v_t - v) \quad \downarrow \int \frac{dx}{x} = \ln x = \ln(v_t - v)$$

$$dx = -dv'$$

$$\ln(v_t - v) = -\frac{k}{m} t \Rightarrow \ln\left(\frac{v_t - v}{v_t}\right) = -\frac{k}{m} t$$

$$\ln a - \ln b = \ln \frac{a}{b} \quad \downarrow$$

$$\frac{v_t - v}{v_t} = e^{-\frac{k}{m} t}$$

$$v(t) = v_t \left(1 - e^{-\frac{k}{m} t} \right)$$

$$t=0 \Rightarrow v=0$$

$$v(t) = v_t$$

$$e^{100} \left(\frac{1}{e^{100}} - \frac{v}{v_t} + 1 \right) = e^{-\frac{k}{m} t}$$

$$a(t) = \frac{dv}{dt} = \left(\frac{k}{m} vt \right) e^{-\frac{k}{m}t} = \underline{g e^{-\frac{k}{m}t}}$$

$$t=0 \rightarrow g$$

$$t \gg 1 \Rightarrow a=0$$

$$x(t) = \int v(t) dt$$

$$x(t) = vt \left[1 - \frac{m}{k} (1 - e^{-\frac{k}{m}t}) \right]$$

At $t \Rightarrow vt = \sqrt{\frac{mg}{D}} \Rightarrow mg \downarrow$ $\uparrow Dv^2 \Rightarrow$ terminal
 $mg - Dv^2 = 0$

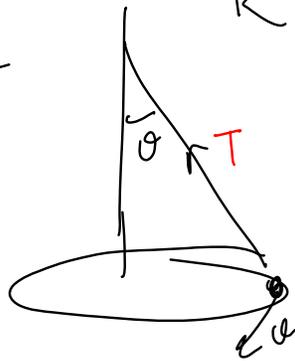
Circular Motion

$$a_{rad} = \frac{v^2}{R}$$

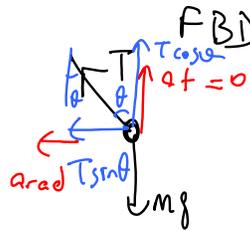
$$T = \frac{2\pi R}{v} \Rightarrow a_{rad} = \frac{4\pi^2 R}{T^2}$$

$$F = m a_{rad} = \frac{m v^2}{R}$$

Example



$mg, v, \theta = ?$



$$\sum F_{\text{top}} = 0 = T \cos \theta - mg \Rightarrow$$

$$\sum F_{\text{rad}} = m a_{rad}$$

$$T \sin \theta = m a_{rad} = \frac{m v^2}{R}$$

$$T \cos \theta = mg \Rightarrow \frac{mg \sin \theta}{\cos \theta} = \frac{m v^2}{R} \Rightarrow \tan \theta = \frac{v^2}{gR}$$

$$\theta = \tan^{-1} \left(\frac{v^2}{gR} \right)$$

