

Take $\nabla \phi = \vec{q}$ and $\vec{q} = -\frac{m_i}{r^2} \vec{n} + \vec{q}_i$; \vec{q}_i velocity at i th point (source) due to other sources, except itself.

$$\sum_{i=1}^n \vec{F}_i = \sum_i p \iint_S \left[\left(-\frac{m_i}{r^2} \vec{n} + \vec{q}_i \right)^2 \vec{n} - \frac{1}{2} \left(-\frac{m_i}{r^2} \vec{n} + \vec{q}_i \right)^2 \vec{n} \right] dS$$

note that $\iint_S \vec{n} dS = 0$; therefore the only term which exists is:

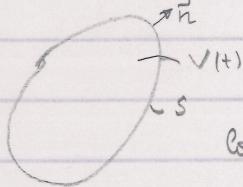
$$\sum_{i=1}^n \vec{F}_i = \sum_i p \frac{m_i}{r^2} \vec{q}_i \iint_S dS = \sum_i 4\pi r^2 p \frac{m_i}{r^2} \vec{q}_i$$

$$= \sum_i 4\pi p m_i \vec{q}_i \quad \text{which proves Biot-Savart's theorem}$$

Here \vec{q}_i is the induced velocity due to the singularities at point singularity i , except the effect of i th singularity.

\vec{F}_i is the force on i th singularity due to all of the singularities.

Transport Theorem: $f(x, t)$ is defined in a general volume surrounded by $S(t)$ which has a normal velocity U_n , and take the specific integral:



$$I(t) = \iiint_V f(x, t) dV$$

Consider a difference in I : $\Delta I = I(t + \Delta t) - I(t)$. Thus

$$\Delta I = \iiint_{V(t+\Delta t)} f(x, t + \Delta t) dV - \iiint_{V(t)} f(x, t) dV. \quad \text{Now expand } f(x, t + \Delta t) \text{ linearly:}$$

$$f(x, t + \Delta t) = f(x, t) + (t + \Delta t - t) \frac{\partial f}{\partial t} + O(\Delta t)^2$$

$$\therefore \Delta I = \iiint_{V(t+\Delta t)} \left(f + \Delta t \frac{\partial f}{\partial t} \right) dV - \iiint_{V(t)} f dV$$

$$= \iiint_{V(t)} \left(f + \Delta t \frac{\partial f}{\partial t} \right) dV + \iiint_{V(t+\Delta t)} \left(f + \Delta t \frac{\partial f}{\partial t} \right) dV - \iiint_{V(t)} f dV = \Delta t \iiint_{V(t)} \frac{\partial f}{\partial t} dV + \iiint_{V(t)} f dV + O(\Delta t)^2$$

$V(\Delta t)$ is the volume between $S(t)$ and $S(t + \Delta t)$. Since the normal vel. is U_n

$$\therefore \Delta I = \Delta t \iiint_V \frac{\partial f}{\partial t} dV + \iint_S (U_n \Delta t) f dS + O[(\Delta t)^2]$$

Divide both sides by Δt and take the limit as $\Delta t \rightarrow 0$

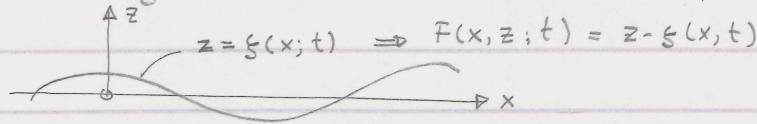
$$\frac{dI}{dt} = \iiint_V \frac{\partial f}{\partial t} dV + \iint_S U_n f dS \quad \text{which gives the Transport Theorem.}$$

If we consider V as a material volume and utilize divergence theorem

$$\frac{d}{dt} \iiint_V f dV = \iiint_V \frac{\partial f}{\partial t} dV + \iint_S (U_n \cdot \vec{n}) f dS = \iiint_V \left\{ \frac{\partial f}{\partial t} + \nabla(f \vec{U}) \cdot \vec{n} \right\} dV$$

FREE SURFACE EFFECTS

a) Linearized B.V.P.



Since the free surface F is a material surface, $\frac{DF}{Dt} = 0$

$$\frac{\partial F}{\partial t} + \frac{\partial \phi}{\partial x} \frac{\partial F}{\partial x} + \frac{\partial \phi}{\partial z} \frac{\partial F}{\partial z} = 0 \quad \text{at } z = \xi(x, t)$$

$$-\frac{\partial \xi}{\partial t} - \frac{\partial \phi}{\partial x} \frac{\partial \xi}{\partial x} + \frac{\partial \phi}{\partial z} = 0 \quad ; \text{ at } z = \xi(x, t). \quad (\text{Namely kinematic f.s. cond.})$$

By using Bernoulli's equation, dynamic free surface cond. is obtained;

$$\frac{P}{\rho} + \frac{1}{2} (\nabla \phi)^2 + g \xi + \frac{\partial \phi}{\partial t} = C(t) = \left(\frac{P_a}{\rho} + 0 \right) \rightarrow \text{at infinity.}$$

∴ Evaluating the L.H.S. at free surface ($P = P_a$) gives;

$$\xi = -\frac{1}{g} \left(\frac{\partial \phi}{\partial t} + \frac{1}{2} (\nabla \phi \cdot \nabla \phi) \right) ; \text{ at } z = \xi.$$

If we neglect quadratic and higher-order terms (assuming that ξ and its slopes is infinitesimally small), kinematic and dynamic boundary cond.s, turn out to be;

$$-\frac{\partial \xi}{\partial t} + \frac{\partial \phi}{\partial z} = 0 ; \text{ at } z = 0$$

$\xi = -\frac{1}{g} \frac{\partial \phi}{\partial t} ; \text{ at } z = 0$. Now take the time derivative of both sides, and substitute the obtained ξ_t in the former;

$$\frac{\partial^2 \phi}{\partial t^2} + g \frac{\partial \phi}{\partial z} = 0 ; \text{ at } z = 0 \quad \text{is obtained as the linearized (2-D)}$$

free surface condition. The same free surface condition can also be obtained - as proposed by Newman - by considering the material derivative of p be vanish at $z = \xi$:

$$\frac{DP}{Dt} = 0 \quad \text{at } z = \xi(x, t).$$

$$\frac{DP}{Dt} = \frac{\partial P}{\partial t} + \frac{\partial \phi}{\partial x} \frac{\partial P}{\partial x} + \frac{\partial \phi}{\partial z} \frac{\partial P}{\partial z} = 0$$

$$= \left(\frac{\partial}{\partial t} + \nabla \phi \cdot \nabla \right) \left(\frac{\partial \phi}{\partial t} + \frac{1}{2} (\nabla \phi)^2 + g \xi \right) = 0 ; \text{ at } z = \xi$$

$$\therefore \frac{\partial^2 \phi}{\partial t^2} + g \frac{\partial \xi}{\partial t} + \nabla \phi \cdot \nabla \frac{\partial \phi}{\partial t} + \frac{1}{2} \nabla \phi \cdot \nabla (\nabla \phi \cdot \nabla \phi) + g \nabla \phi \cdot \nabla \xi = 0 ; \text{ at } z = \xi$$

Note that from kinematic b.c. $\partial \xi / \partial t = \frac{\partial \phi}{\partial z}$, then by neglecting higher-order terms:

$$\frac{\partial^2 \phi}{\partial t^2} + g \frac{\partial \phi}{\partial z} = 0 \quad \text{at } z = 0.$$