

Discrete Mathematics

Graphs

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Topics

Graphs

Introduction
Walks
Connectivity
Planar Graphs

Graph Problems

Graph Coloring
Shortest Path
TSP
Searching Graphs

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Graphs

Definition

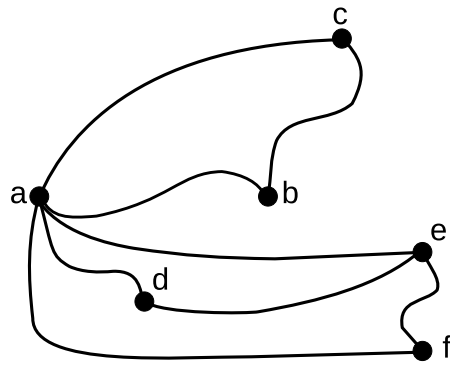
graph: $G = (V, E)$

- ▶ V : **node** (or *vertex*) set
- ▶ $E \subseteq V \times V$: **edge** set

- ▶ $e = (v_1, v_2) \in E$:
- ▶ v_1 and v_2 are *endnodes* of e
- ▶ e is *incident* to v_1 and v_2
- ▶ v_1 and v_2 are *adjacent*

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Graph Example



$$\begin{aligned} V &= \{a, b, c, d, e, f\} \\ E &= \{(a, b), (a, c), \\ &\quad (a, d), (a, e), \\ &\quad (a, f), (b, c), \\ &\quad (d, e), (e, f)\} \end{aligned}$$

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Directed Graphs

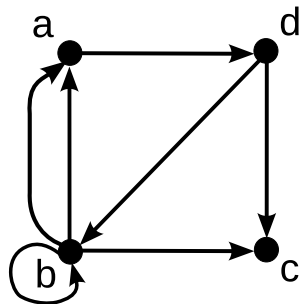
Definition

directed graph (*digraph*): $D = (V, A)$

- ▶ V : node set
- ▶ $A \subseteq V \times V$: **arc** set
- ▶ $a = (v_1, v_2) \in A$:
- ▶ v_1 : *origin* node of a
- ▶ v_2 : *terminating* node of a

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Directed Graph Example



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Weighted Graphs

- ▶ weighted graph: labels assigned to edges
- ▶ weight
- ▶ length, distance
- ▶ cost, delay
- ▶ probability
- ▶ ...

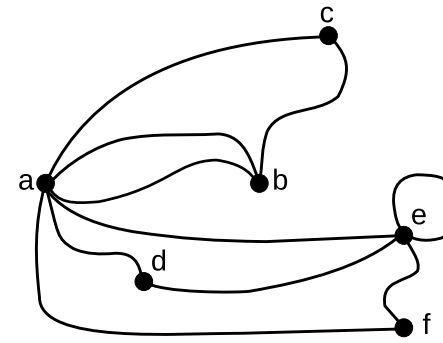
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Multigraphs

- ▶ **parallel edges**: edges between same node pair
- ▶ **loop**: edge starting and ending in same node
- ▶ **plain** graph: no loops, no parallel edges
- ▶ **multigraph**: a graph which is not plain

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Multigraph Example



- ▶ parallel edges: (a, b)
- ▶ loop: (e, e)

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Subgraph

Definition

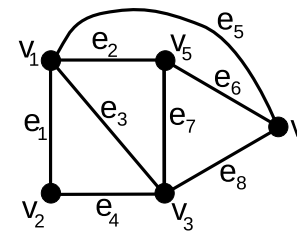
$G' = (V', E')$ is a **subgraph** of $G = (V, E)$:
 $V' \subseteq V \wedge E' \subseteq E \wedge \forall (v_1, v_2) \in E' [v_1, v_2 \in V']$

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Incidence Matrix

- ▶ rows: nodes, columns: edges
- ▶ 1 if edge incident on node, 0 otherwise

example



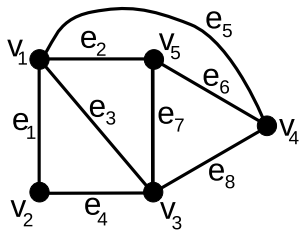
	e_1	e_2	e_3	e_4	e_5	e_6	e_7	e_8
v_1	1	1	1	0	1	0	0	0
v_2	1	0	0	1	0	0	0	0
v_3	0	0	1	1	0	0	1	1
v_4	0	0	0	0	1	1	0	1
v_5	0	1	0	0	0	1	1	0

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Adjacency Matrix

- rows: nodes, columns: nodes
- 1 if nodes are adjacent, 0 otherwise

example



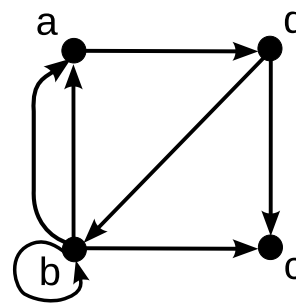
	v_1	v_2	v_3	v_4	v_5
v_1	0	1	1	1	1
v_2	1	0	1	0	0
v_3	1	1	0	1	1
v_4	1	0	1	0	1
v_5	1	0	1	1	0

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Adjacency Matrix

- multigraph: number of edges between nodes

example



	a	b	c	d
a	0	0	0	1
b	2	1	1	0
c	0	0	0	0
d	0	1	1	0

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Adjacency Matrix

- weighted graph: weight of edge

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Degree

- degree of node: number of incident edges

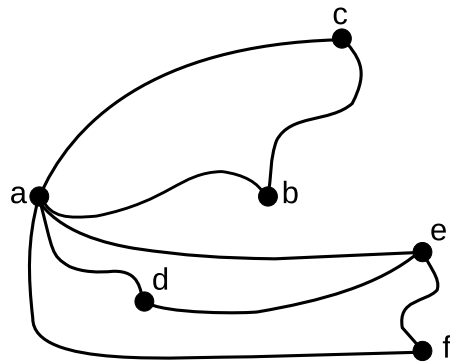
Theorem

d_v : degree of node v

$$|E| = \frac{\sum_{v \in V} d_v}{2}$$

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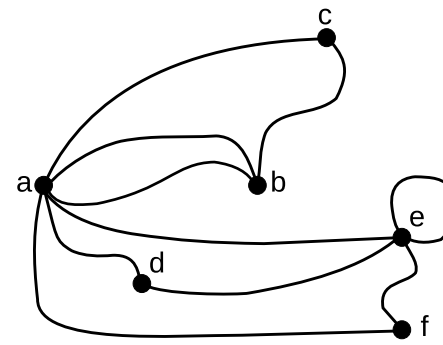
Degree Example



$$\begin{array}{rcl}
 d_a & = & 5 \\
 d_b & = & 2 \\
 d_c & = & 2 \\
 d_d & = & 2 \\
 d_e & = & 3 \\
 d_f & = & 2 \\
 \hline
 & & 16 \\
 |E| & = & 8
 \end{array}$$

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Multigraph Degree Example



$$\begin{array}{rcl}
 d_a & = & 6 \\
 d_b & = & 3 \\
 d_c & = & 2 \\
 d_d & = & 2 \\
 d_e & = & 5 \\
 d_f & = & 2 \\
 \hline
 & & 20 \\
 |E| & = & 10
 \end{array}$$

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Degree in Directed Graphs

- ▶ in-degree: d_v^i
- ▶ out-degree: d_v^o
- ▶ node with in-degree 0: *source*
- ▶ node with out-degree 0: *sink*
- ▶ $\sum_{v \in V} d_v^i = \sum_{v \in V} d_v^o = |A|$

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Degree

Theorem

In an undirected graph, there is an even number of nodes which have an odd degree.

Proof.

- ▶ t_i : number of nodes of degree i
- $2|E| = \sum_{v \in V} d_v = 1t_1 + 2t_2 + 3t_3 + 4t_4 + 5t_5 + \dots$
- $2|E| - 2t_2 - 4t_4 - \dots = t_1 + t_3 + t_5 + \dots + 2t_3 + 4t_5 + \dots$
- $2|E| - 2t_2 - 4t_4 - \dots - 2t_3 - 4t_5 - \dots = t_1 + t_3 + t_5 + \dots$
- ▶ left-hand side even $\Rightarrow$ right-hand side even

□

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Isomorphism

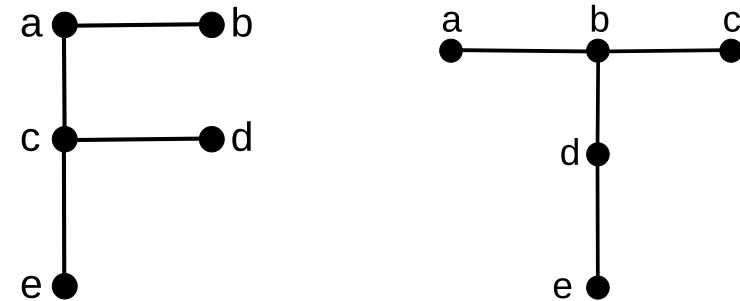
Definition

$G = (V, E)$ and $G^* = (V^*, E^*)$ are **isomorphic**:
 $\exists f : V \rightarrow V^* [(u, v) \in E \Rightarrow (f(u), f(v)) \in E^*] \wedge f$ is bijective

- G and G^* can be drawn the same way

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Isomorphism Example



- $f = (a \mapsto d, b \mapsto e, c \mapsto b, d \mapsto c, e \mapsto a)$

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Petersen Graph



- $f = (a \mapsto q, b \mapsto v, c \mapsto u, d \mapsto y, e \mapsto r, f \mapsto w, g \mapsto x, h \mapsto t, i \mapsto z, j \mapsto s)$

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Homeomorphism

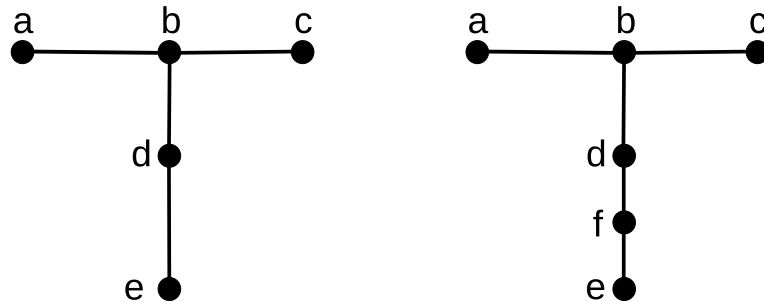
Definition

$G = (V, E)$ and $G^* = (V^*, E^*)$ are **homeomorphic**:

- G and G^* isomorphic, except that
- some edges in E^* are divided with additional nodes

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Homeomorphism Example

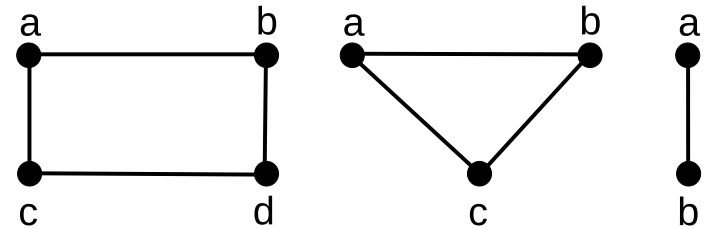


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Regular Graphs

- ▶ **regular** graph: all nodes have the same degree
- ▶ n -regular: all nodes have degree n

examples



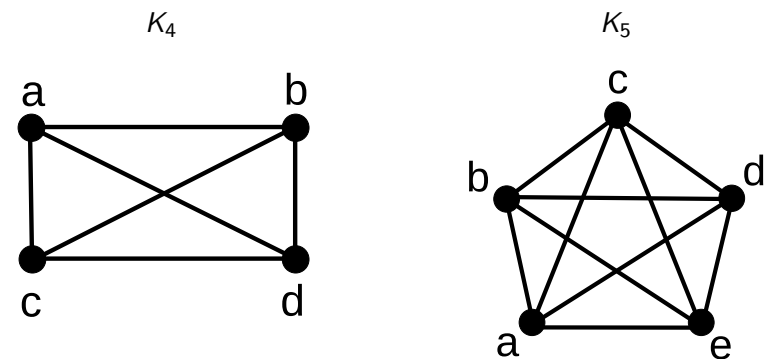
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Completely Connected Graphs

- ▶ $G = (V, E)$ is **completely connected**:
 $\forall v_1, v_2 \in V (v_1, v_2) \in E$
- ▶ every pair of nodes are adjacent
- ▶ K_n : completely connected graph with n nodes

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Completely Connected Graph Examples

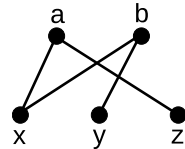


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Bipartite Graphs

- ▶ $G = (V, E)$ is **bipartite**: $V_1 \cup V_2 = V$, $V_1 \cap V_2 = \emptyset$
 $\forall (v_1, v_2) \in E [v_1 \in V_1 \wedge v_2 \in V_2]$

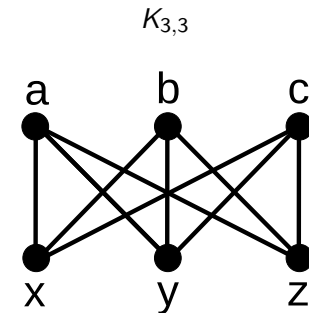
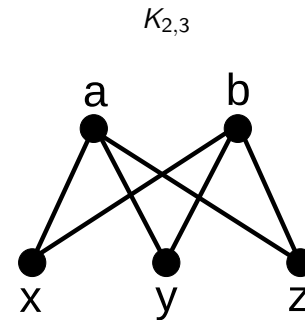
example



- ▶ *complete bipartite*: $\forall v_1 \in V_1 \forall v_2 \in V_2 (v_1, v_2) \in E$
- ▶ $K_{m,n}$: $|V_1| = m$, $|V_2| = n$

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Complete Bipartite Graph Examples



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Walk

- ▶ **walk**: sequence of nodes and edges
 from a starting node (v_0) to an ending node (v_n)

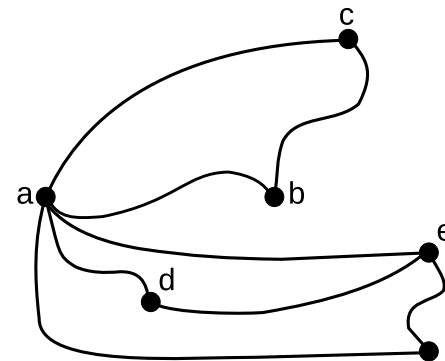
$$v_0 \xrightarrow{e_1} v_1 \xrightarrow{e_2} v_2 \xrightarrow{e_3} v_3 \rightarrow \dots \rightarrow v_{n-1} \xrightarrow{e_n} v_n$$

where $e_i = (v_{i-1}, v_i)$

- ▶ no need to write the edges if not weighted
- ▶ **length**: number of edges
- ▶ $v_0 = v_n$: **closed**

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Walk Example



$$\begin{array}{l} c \xrightarrow{(c,b)} b \xrightarrow{(b,a)} a \xrightarrow{(a,d)} d \\ \xrightarrow{(d,e)} e \xrightarrow{(e,f)} f \xrightarrow{(f,a)} a \\ \xrightarrow{(a,b)} b \end{array}$$

$$\begin{array}{l} c \rightarrow b \rightarrow a \rightarrow d \rightarrow e \\ \rightarrow f \rightarrow a \rightarrow b \end{array}$$

length: 7

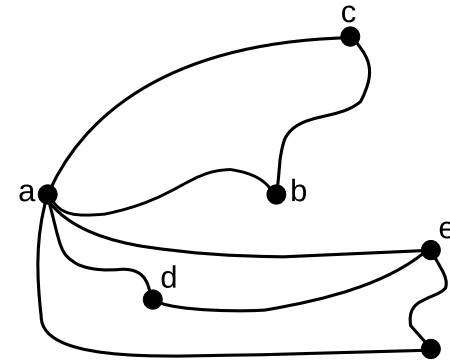
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Trail

- ▶ **trail**: edges not repeated
- ▶ **circuit**: closed trail
- ▶ **spanning trail**: covers all edges

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Trail Example



$$\begin{array}{l}
 c \xrightarrow{(c,b)} b \xrightarrow{(b,a)} a \xrightarrow{(a,e)} e \\
 \xrightarrow{(e,d)} d \xrightarrow{(d,a)} a \xrightarrow{(a,f)} f \\
 c \rightarrow b \rightarrow a \rightarrow e \rightarrow d \rightarrow a \rightarrow f
 \end{array}$$

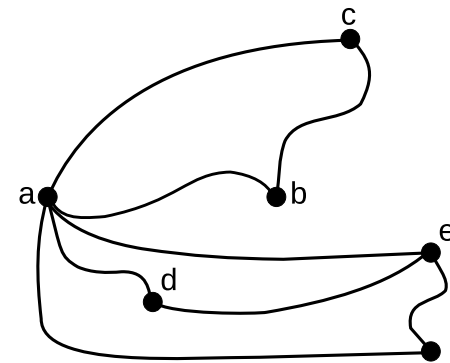
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Path

- ▶ **path**: nodes not repeated
- ▶ **cycle**: closed path
- ▶ **spanning path**: visits all nodes

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Path Example



$$\begin{array}{l}
 c \xrightarrow{(c,b)} b \xrightarrow{(b,a)} a \xrightarrow{(a,d)} d \\
 \xrightarrow{(d,e)} e \xrightarrow{(e,f)} f \\
 c \rightarrow b \rightarrow a \rightarrow d \rightarrow e \rightarrow f
 \end{array}$$

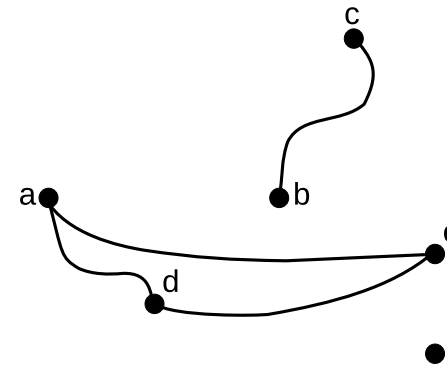
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Connected Graphs

- ▶ **connected**: a path between every pair of nodes
- ▶ a disconnected graph can be divided into connected components

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Connected Components Example



- ▶ disconnected: no path between a and c
- ▶ connected components:
 a, d, e
 b, c
 f

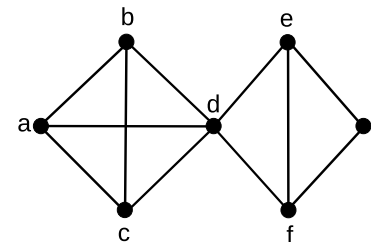
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Distance

- ▶ **distance** between v_i and v_j : length of shortest path between v_i and v_j
- ▶ **diameter** of graph: largest distance in graph

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Distance Example



- ▶ distance between a and e : 2
- ▶ diameter: 3

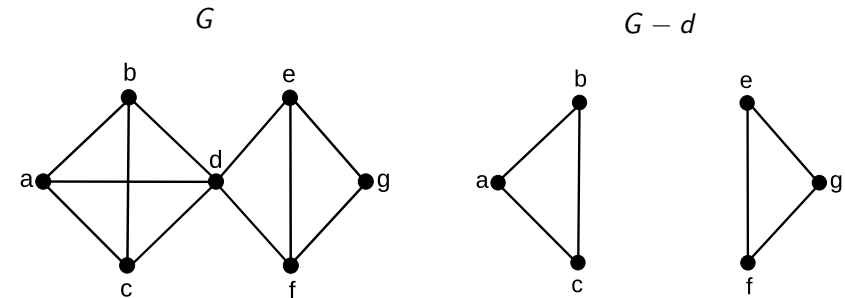
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Cut-Points

- ▶ $G - v$: delete v and all its incident edges from G
- ▶ v is a **cut-point** for G :
 G is connected but $G - v$ is not

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Cut-Point Example



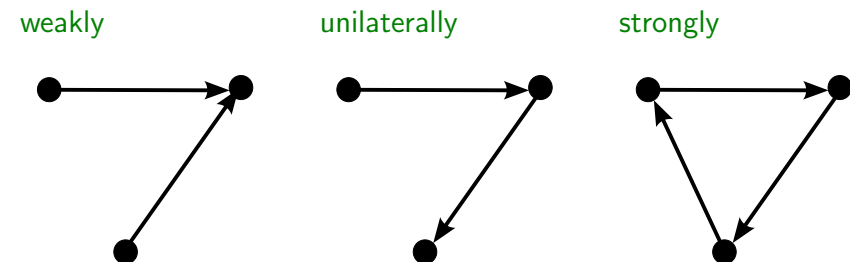
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Directed Walks

- ▶ ignoring directions on arcs: *semi-walk*, *semi-trail*, *semi-path*
- ▶ if between every pair of nodes there is:
 - ▶ a semi-path: **weakly** connected
 - ▶ a path from one to the other: **unilaterally** connected
 - ▶ a path: **strongly** connected

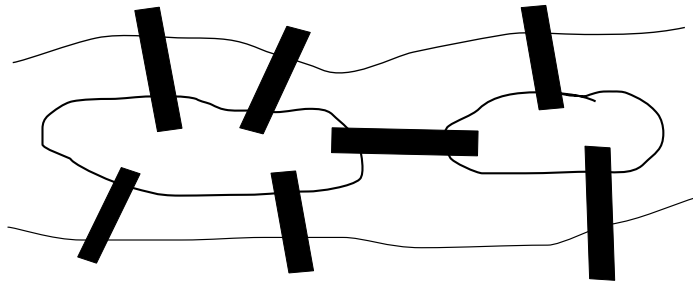
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Directed Graph Examples



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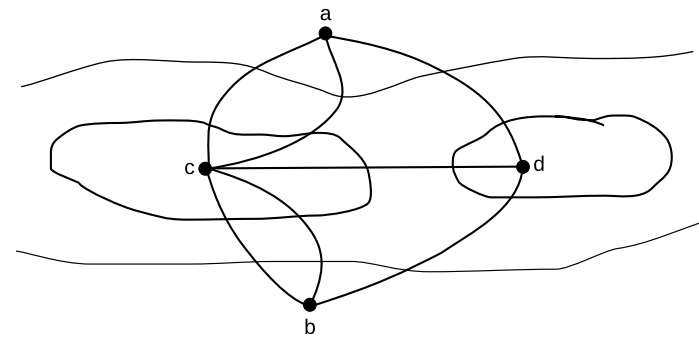
Bridges of Königsberg



- cross each bridge exactly once and return to the starting point

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Graphs



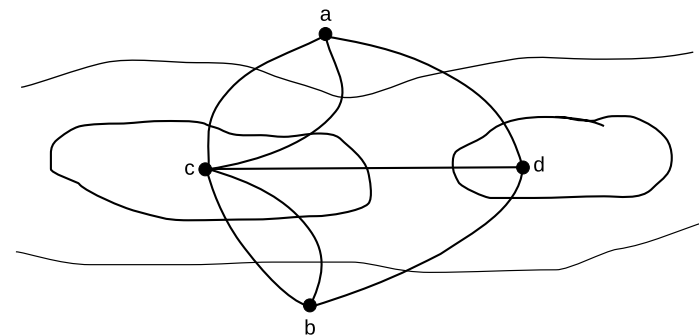
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Traversable Graphs

- G is **traversable**: G contains a spanning trail
- a node with an odd degree must be either the starting node or the ending node of the trail
- all nodes except the starting node and the ending node must have even degrees

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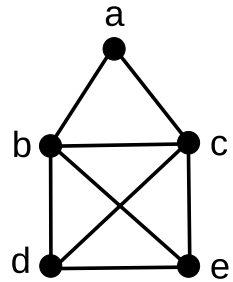
Bridges of Königsberg



- all nodes have odd degrees: not traversable

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Traversable Graph Example



- ▶ a, b, c : even
- ▶ d, e : odd
- ▶ start from d , end at e :
 $d \rightarrow b \rightarrow a \rightarrow c \rightarrow e$
 $\rightarrow d \rightarrow c \rightarrow b \rightarrow e$

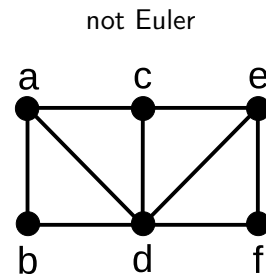
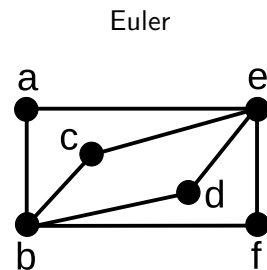
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Euler Graphs

- ▶ **Euler graph**: contains closed spanning trail
- ▶ G is an Euler graph $\Leftrightarrow$ all nodes in G have even degrees

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Euler Graph Examples



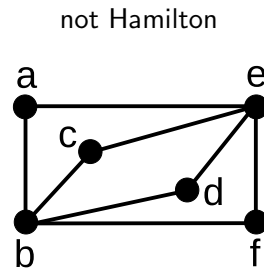
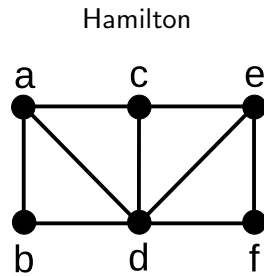
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Hamilton Graphs

- ▶ **Hamilton graph**: contains a closed spanning path

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Hamilton Graph Examples



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Connectivity Matrix

- ▶ A : adjacency matrix of $G = (V, E)$
- ▶ A_{ij}^k : number of walks of length k between v_i and v_j
- ▶ maximum distance between two nodes: $|V| - 1$
- ▶ connectivity matrix:

$$C = A^1 + A^2 + A^3 + \dots + A^{|V|-1}$$
- ▶ connected: all elements of C are non-zero

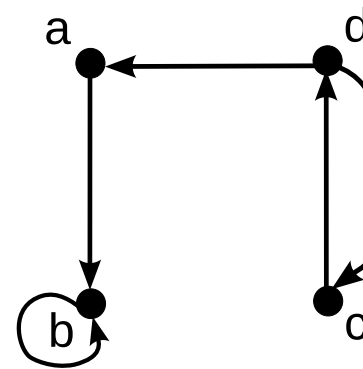
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Warshall's Algorithm

- ▶ very expensive to compute the connectivity matrix
- ▶ easier to find whether there is a walk between two nodes rather than finding the number of walks
- ▶ for each node:
- ▶ from all nodes which can reach the current node (rows that contain 1 in current column)
- ▶ to all nodes which can be reached from the current node (columns that contain 1 in current row)

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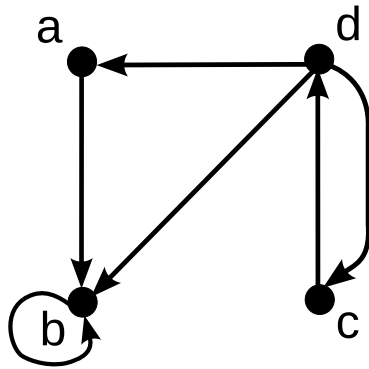
Warshall's Algorithm Example



	a	b	c	d
a	0	1	0	0
b	0	1	0	0
c	0	0	0	1
d	1	0	1	0

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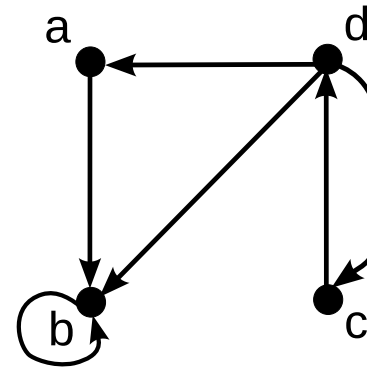
Warshall's Algorithm Example



	a	b	c	d
a	0	1	0	0
b	0	1	0	0
c	0	0	0	1
d	1	1	1	0

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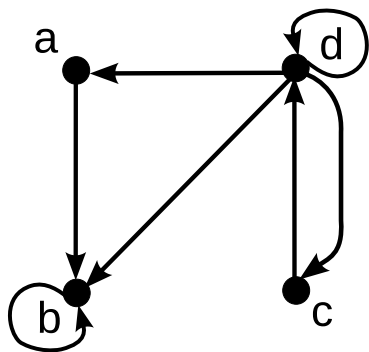
Warshall's Algorithm Example



	a	b	c	d
a	0	1	0	0
b	0	1	0	0
c	0	0	0	1
d	1	1	1	0

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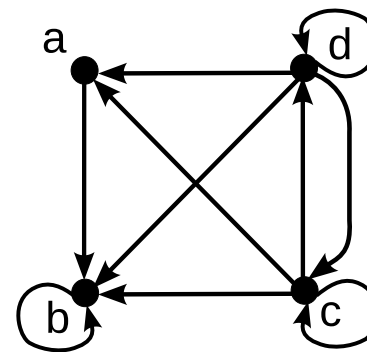
Warshall's Algorithm Example



	a	b	c	d
a	0	1	0	0
b	0	1	0	0
c	0	0	0	1
d	1	1	1	1

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Warshall's Algorithm Example



	a	b	c	d
a	0	1	0	0
b	0	1	0	0
c	1	1	1	1
d	1	1	1	1

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Planar Graphs

Definition

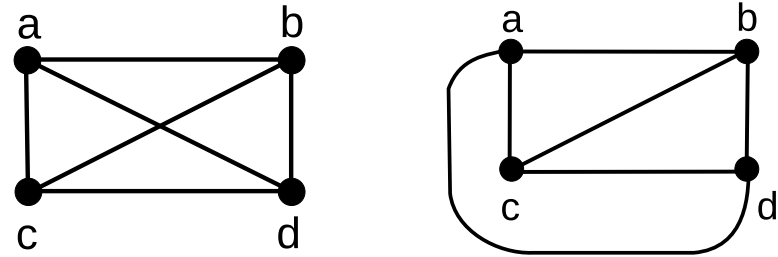
G is **planar**:

G can be drawn on a plane without intersecting its edges

- ▶ a **map** of G : a planar drawing of G

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Planar Graph Example



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Regions

- ▶ map divides plane into **regions**
- ▶ degree of region: length of closed trail that surrounds region

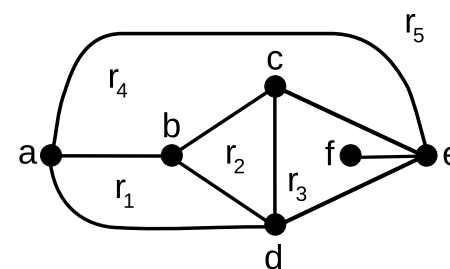
Theorem

d_{r_i} : degree of region r_i

$$|E| = \frac{\sum_i d_{r_i}}{2}$$

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Region Example



d_{r_1}	=	3
d_{r_2}	=	3
d_{r_3}	=	5
d_{r_4}	=	4
d_{r_5}	=	3
	=	18
$ E $	=	9

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Euler's Formula

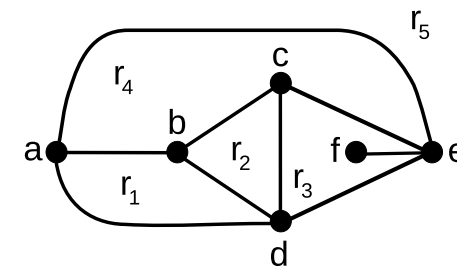
Theorem (Euler's Formula)

$G = (V, E)$: planar, connected graph
 R : set of regions in a map of G

$$|V| - |E| + |R| = 2$$

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Euler's Formula Example



► $|V| = 6, |E| = 9, |R| = 5$

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Planar Graph Theorems

Theorem

$G = (V, E)$: connected, planar graph where $|V| \geq 3$
 $|E| \leq 3|V| - 6$

Proof.

- sum of region degrees: $2|E|$
- degree of a region ≥ 3
 $\Rightarrow 2|E| \geq 3|R| \Rightarrow |R| \leq \frac{2}{3}|E|$
- $|V| - |E| + |R| = 2$
 $\Rightarrow |V| - |E| + \frac{2}{3}|E| \geq 2 \Rightarrow |V| - \frac{1}{3}|E| \geq 2$
 $\Rightarrow 3|V| - |E| \geq 6 \Rightarrow |E| \leq 3|V| - 6$

□

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Planar Graph Theorems

Theorem

$G = (V, E)$: connected, planar graph where $|V| \geq 3$:
 $\exists v \in V [d_v \leq 5]$

Proof.

- assume: $\forall v \in V [d_v \geq 6]$
 $\Rightarrow 2|E| \geq 6|V|$
 $\Rightarrow |E| \geq 3|V|$
 $\Rightarrow |E| > 3|V| - 6$

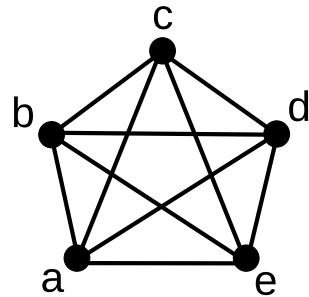
□

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Nonplanar Graphs

Theorem

K_5 is not planar.



Proof.

- ▶ $|V| = 5$
- ▶ $3|V| - 6 = 3 \cdot 5 - 6 = 9$
- ▶ $|E| \leq 9$ should hold
- ▶ but $|E| = 10$

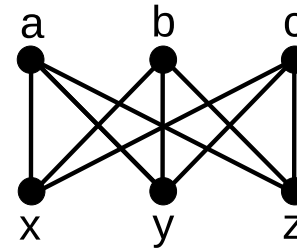
□

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Nonplanar Graphs

Theorem

$K_{3,3}$ is not planar.



Proof.

- ▶ $|V| = 6, |E| = 9$
- ▶ if planar then $|R| = 5$
- ▶ degree of a region ≥ 4
 $\Rightarrow \sum_{r \in R} d_r \geq 20$
- ▶ $|E| \geq 10$ should hold
- ▶ but $|E| = 9$

□

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Kuratowski's Theorem

Theorem

G contains a subgraph homeomorphic to K_5 or $K_{3,3}$.

$\Leftrightarrow$

G is not planar.

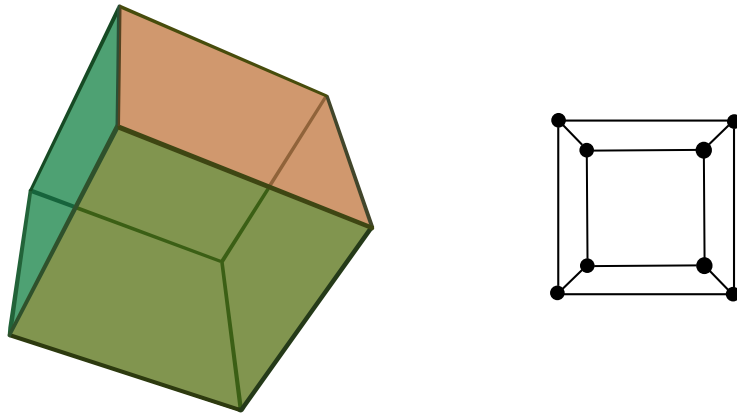
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Platonic Solids

- ▶ *regular polyhedron*: a 3-dimensional solid where faces are identical regular polygons
- ▶ projection of a regular polyhedron onto the plane: a planar graph
- ▶ corners: nodes
- ▶ sides: edges
- ▶ faces: regions

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Platonic Solid Example



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Platonic Solids

- ▶ $|V|$: number of corners (nodes)
- ▶ $|E|$: number of sides (edges)
- ▶ $|R|$: number of faces (regions)
- ▶ n : number of faces meeting at a corner (node degree)
- ▶ m : number of sides of a face (region degree)
- ▶ $m, n \geq 3$
- ▶ $2|E| = n \cdot |V|$
- ▶ $2|E| = m \cdot |R|$

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Platonic Solids

- ▶ from Euler's formula:

$$2 = |V| - |E| + |R| = \frac{2|E|}{n} - |E| + \frac{2|E|}{m} = |E| \left(\frac{2m - mn + 2n}{mn} \right) > 0$$

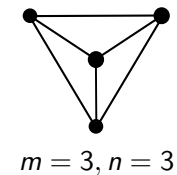
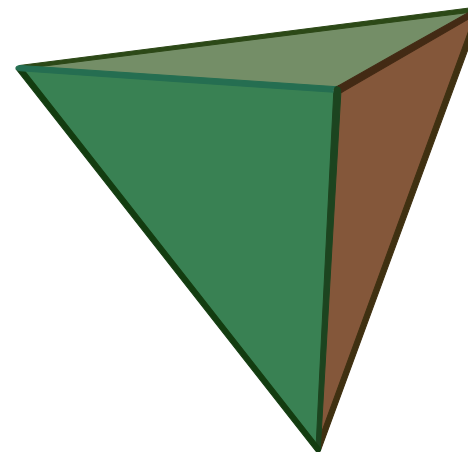
- ▶ $|E|, m, n > 0$:

$$\begin{aligned} 2m - mn + 2n > 0 &\Rightarrow mn - 2m - 2n < 0 \\ &\Rightarrow mn - 2m - 2n + 4 < 4 \Rightarrow (m-2)(n-2) < 4 \end{aligned}$$

- ▶ only 5 solutions

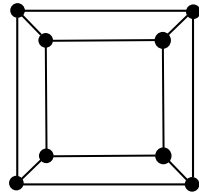
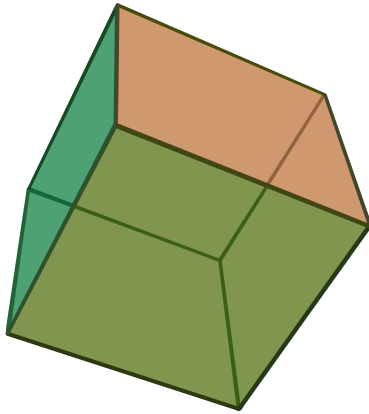
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Tetrahedron



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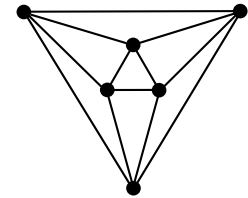
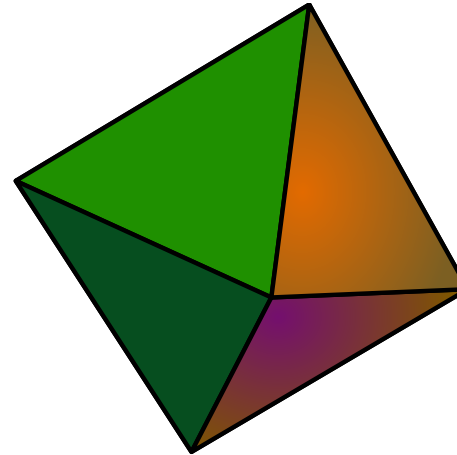
Hexahedron



$$m = 4, n = 3$$

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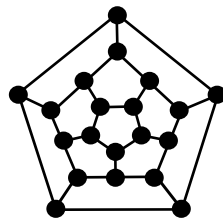
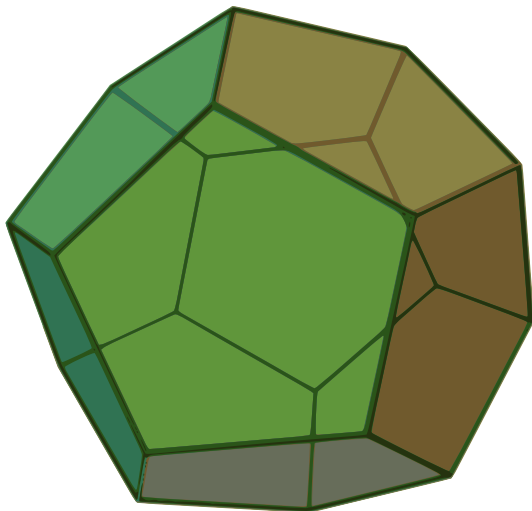
Octahedron



$$m = 3, n = 4$$

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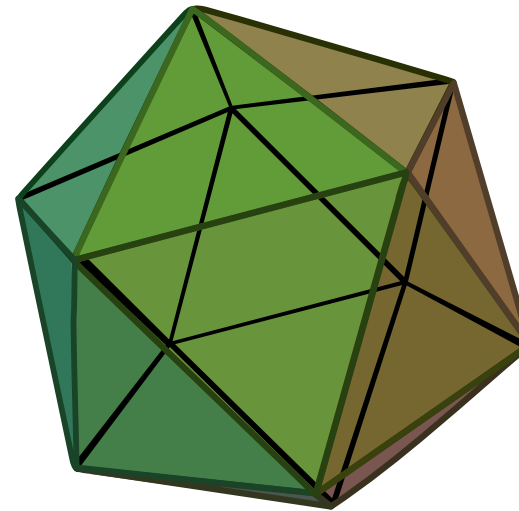
Dodecahedron



$$m = 5, n = 3$$

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Icosahedron



$$m = 3, n = 5$$

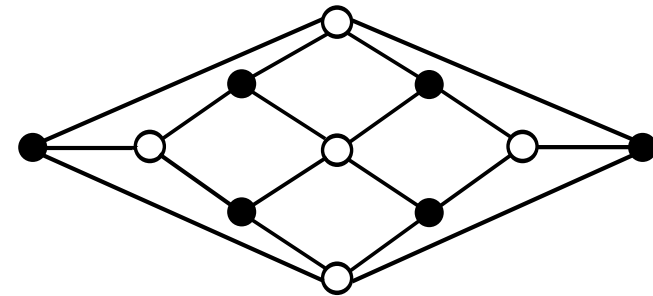
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Graph Coloring

- ▶ $G = (V, E)$, C : set of colors
- ▶ **proper coloring** of G : find an $f : V \rightarrow C$, such that $\forall (v_i, v_j) \in E [f(v_i) \neq f(v_j)]$
- ▶ **chromatic number** of G : $\chi(G)$
minimum $|C|$
- ▶ finding $\chi(G)$ is a very difficult problem
- ▶ $\chi(K_n) = n$

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Chromatic Number Example



- ▶ Herschel graph: $\chi(G) = 2$

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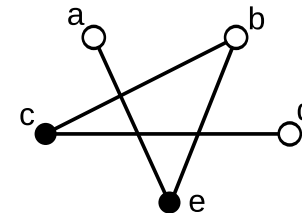
Graph Coloring Example

- ▶ a company produces chemical compounds
- ▶ some compounds cannot be stored together
- ▶ such compounds must be placed in separate storage areas
- ▶ store compounds using minimum number of storage areas

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Graph Coloring Example

- ▶ every compound is a node
- ▶ two compounds that cannot be stored together are adjacent



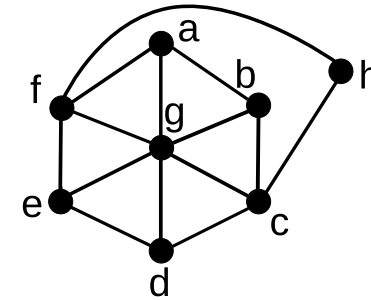
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Graph Coloring Solution

- ▶ pick a node and assign a color
- ▶ assign same color to all nodes with no conflict
- ▶ pick an uncolored node and assign a second color
- ▶ assign same color to all uncolored nodes with no conflict
- ▶ pick an uncolored node and assign a third color
- ▶ ...

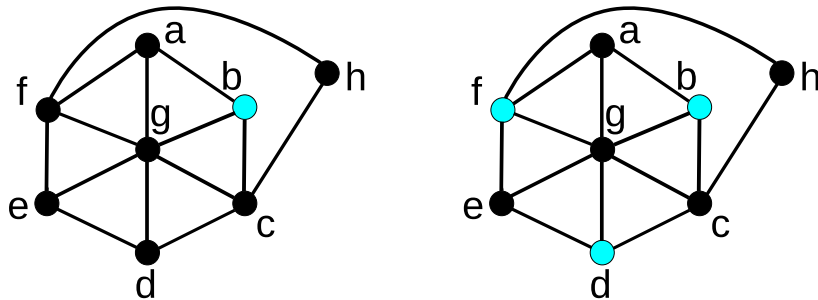
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Graph Coloring Example



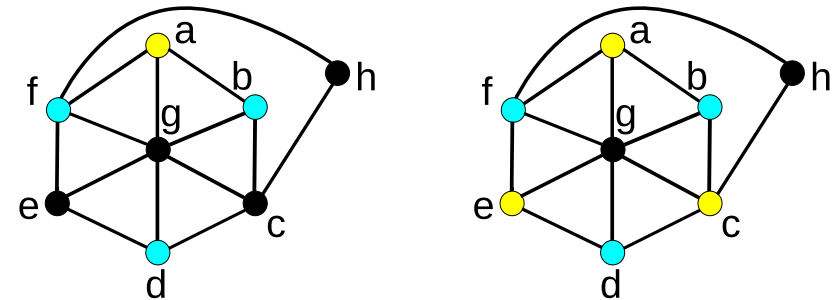
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Graph Coloring Example



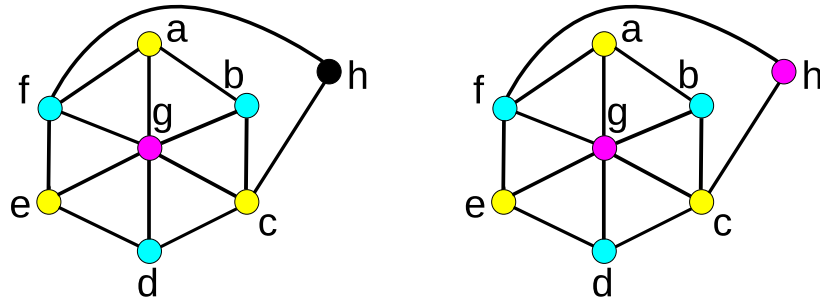
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Graph Coloring Example



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Graph Coloring Example



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Heuristic Solutions

- ▶ **heuristic** solution: based on intuition
- ▶ **greedy** solution: doesn't look ahead
- ▶ doesn't produce optimal results

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Graph Coloring Example: Sudoku

5	3			7				
6			1	9	5			
	9	8					6	
8				6				3
4			8		3			1
7				2				6
	6					2	8	
			4	1	9			5
				8			7	9

- ▶ every cell is a node
- ▶ cells of the same row are adjacent
- ▶ cells of the same column are adjacent
- ▶ cells of the same 3×3 block are adjacent
- ▶ every number is a color
- ▶ problem: properly color a graph that is partially colored

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Region Coloring

- ▶ coloring a map by assigning different colors to adjacent regions

Theorem (Four Color Theorem)

The regions in a map can be colored using four colors.

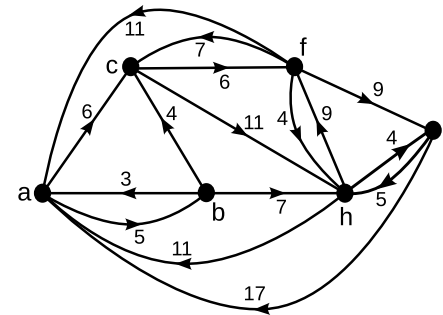
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Shortest Path

- ▶ finding shortest paths from a starting node to all other nodes: Dijkstra's algorithm

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Dijkstra's Algorithm Example

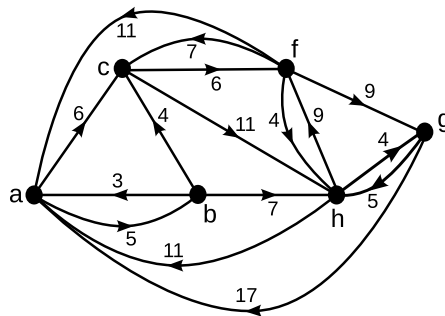


- ▶ starting node: c

a	$(\infty, -)$
b	$(\infty, -)$
c	$(0, -)$
f	$(\infty, -)$
g	$(\infty, -)$
h	$(\infty, -)$

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Dijkstra's Algorithm Example



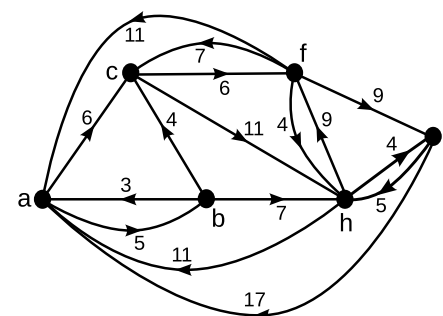
- ▶ from c: base distance=0
- ▶ $c \rightarrow f : 6, 6 < \infty$
- ▶ $c \rightarrow h : 11, 11 < \infty$

a	$(\infty, -)$	
b	$(\infty, -)$	
c	$(0, -)$	✓
f	$(6, cf)$	
g	$(\infty, -)$	
h	$(11, ch)$	

- ▶ closest node: f

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Dijkstra's Algorithm Example



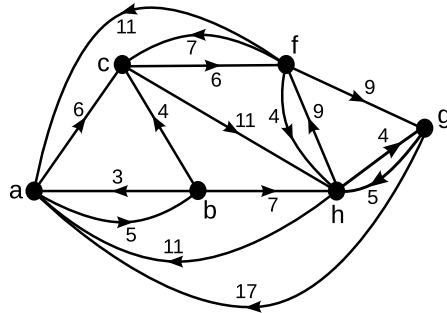
- ▶ from f: base distance=6
- ▶ $f \rightarrow a : 6 + 11, 17 < \infty$
- ▶ $f \rightarrow g : 6 + 9, 15 < \infty$
- ▶ $f \rightarrow h : 6 + 4, 10 < 11$

a	$(17, cfa)$	
b	$(\infty, -)$	
c	$(0, -)$	✓
f	$(6, cf)$	✓
g	$(15, cfg)$	
h	$(10, cfh)$	

- ▶ closest node: h

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Dijkstra's Algorithm Example



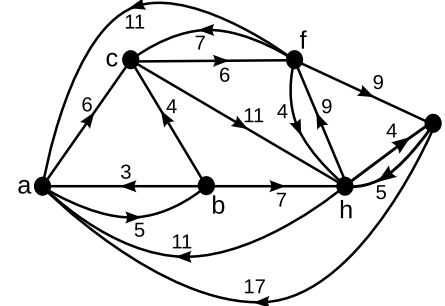
- ▶ from h : base distance=10
- ▶ $h \rightarrow a$: $10 + 11, 21 \not< 17$
- ▶ $h \rightarrow g$: $10 + 4, 14 < 15$

a	(17, cfa)	
b	(∞ , -)	
c	(0, -)	✓
f	(6, cf)	✓
g	(14, cfhg)	✓
h	(10, cfh)	✓

- ▶ closest node: g

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Dijkstra's Algorithm Example



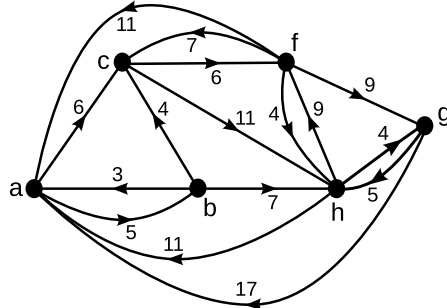
- ▶ from g : base distance=14
- ▶ $g \rightarrow a$: $14 + 17, 31 \not< 17$

a	(17, cfa)	
b	(∞ , -)	
c	(0, -)	✓
f	(6, cf)	✓
g	(14, cfhg)	✓
h	(10, cfh)	✓

- ▶ closest node: a

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Dijkstra's Algorithm Example



- ▶ from a : base distance=17
- ▶ $a \rightarrow b$: $17 + 5, 22 < \infty$

a	(17, cfa)	✓
b	(22, cfab)	
c	(0, -)	✓
f	(6, cf)	✓
g	(14, cfhg)	✓
h	(10, cfh)	✓

- ▶ last node: b

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Traveling Salesperson Problem

- ▶ start from a home town
- ▶ visit every city exactly once
- ▶ return to the home town
- ▶ minimum total distance
- ▶ find Hamiltonian cycle
- ▶ very difficult problem

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TSP Solution

- ▶ heuristic: nearest-neighbor

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Searching Graphs

- ▶ searching nodes of graph $G = (V, E)$ starting from node v_1
- ▶ depth-first
- ▶ breadth-first

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Depth-First Search

1. $v \leftarrow v_1, T = \emptyset, D = \{v_1\}$
2. find smallest i in $2 \leq i \leq |V|$ such that $(v, v_i) \in E$ and $v_i \notin D$
 - ▶ if no such i : go to step 3
 - ▶ if found: $T = T \cup \{(v, v_i)\}, D = D \cup \{v_i\}, v \leftarrow v_i$, go to step 2
3. if $v = v_1$: result is T
4. if $v \neq v_1$: $v \leftarrow \text{backtrack}(v)$, go to step 2

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Breadth-First Search

1. $T = \emptyset, D = \{v_1\}, Q = (v_1)$
2. if Q empty: result is T
3. if Q not empty: $v \leftarrow \text{front}(Q), Q \leftarrow Q - v$
for $2 \leq i \leq |V|$ check edges $(v, v_i) \in E$:
 - ▶ if $v_i \notin D$: $Q = Q + v_i, T = T \cup \{(v, v_i)\}, D = D \cup \{v_i\}$
 - ▶ go to step 3

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References

Required Reading: Grimaldi

- ▶ Chapter 11: [An Introduction to Graph Theory](#)
- ▶ Chapter 7: Relations: The Second Time Around
 - ▶ 7.2. [Computer Recognition: Zero-One Matrices and Directed Graphs](#)
- ▶ Chapter 13: Optimization and Matching
 - ▶ 13.1. [Dijkstra's Shortest Path Algorithm](#)