

Plotting and Transforming a Circle in 3D

$$x_c := 2 \quad r := 5 \quad x(t) := r \cdot \cos(t) + x_c \quad s := 4 \quad n := 4 \quad j := 0..n \quad t_j := \frac{j \cdot 2 \cdot \pi}{n}$$

$$y_c := 3 \quad y(t) := r \cdot \sin(t) + y_c$$

$$z(t) := 0$$

$$T := \begin{pmatrix} 1 & 0 & 0 & x_c \\ 0 & 1 & 0 & y_c \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad T1 := \begin{pmatrix} 1 & 0 & 0 & -x_c \\ 0 & 1 & 0 & -y_c \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$P_{0,j} := x(t_j) \quad P_{0,n+j+1} := x(t_j)$$

$$P_{1,j} := y(t_j) \quad P_{1,n+j+1} := y(t_j)$$

$$P_{2,j} := z(t_j) \quad P_{2,n+j+1} := z(t_j) + 5$$

$$P_{3,j} := 1 \quad P_{3,n+j+1} := 1$$

$$x = r \cdot \cos(\theta)$$

$$y = r \cdot \sin(\theta)$$

$$x' = r \cdot \cos(\theta + \alpha) = r \cdot \cos(\alpha) \cdot \cos(\theta) - r \cdot \sin(\alpha) \cdot \sin(\theta)$$

$$y' = r \cdot \sin(\theta + \alpha) = r \cdot \sin(\alpha) \cdot \cos(\theta) + r \cdot \cos(\alpha) \cdot \sin(\theta)$$

$$x' = x \cdot \cos(\theta) - y \cdot \sin(\theta)$$

$$y' = x \cdot \sin(\theta) + y \cdot \cos(\theta)$$

$$\begin{pmatrix} x' & y' \end{pmatrix} = \begin{pmatrix} x & y \end{pmatrix} \cdot \begin{pmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{pmatrix}$$

$$Rx(\theta) := \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(\theta) & -\sin(\theta) & 0 \\ 0 & \sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad Mirr := \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$Rz(\theta) := \begin{pmatrix} \cos(\theta) & -\sin(\theta) & 0 & 0 \\ \sin(\theta) & \cos(\theta) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$Ry(\theta) := \begin{pmatrix} \cos(\theta) & 0 & \sin(\theta) & 0 \\ 0 & 1 & 0 & 0 \\ -\sin(\theta) & 0 & \cos(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$i:=0..3 \qquad k:=0..\frac{\text{cols}(P)}{4}$$

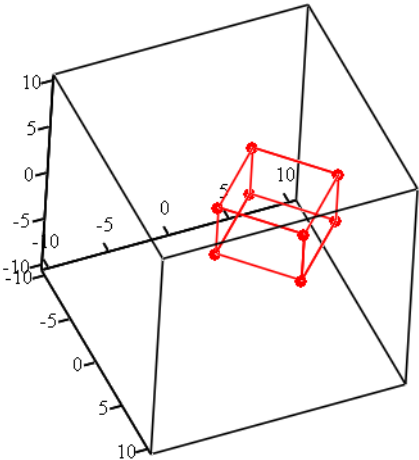
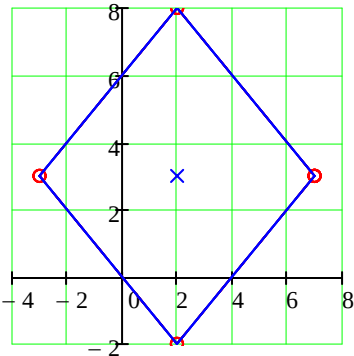
$$PP_{i,2\cdot j}:=P_{i,j} \qquad PP_{i,2\cdot j+1}:=P_{i,n+1+j} \qquad PPP:=PP$$

$$PPP_{i,4\cdot k}:=PP_{i,4\cdot k+1} \qquad PPP_{i,4\cdot k+1}:=PP_{i,4\cdot k}$$

$$P:=\text{augment}(P,PPP)$$

$$p:=Rz\left(\frac{2\cdot\pi\cdot2}{10}\right)\cdot P \quad \theta:=\frac{\pi\cdot\text{FRAME}}{20}$$

$$p:=T\cdot Rz(\theta)\cdot T1\cdot P \qquad p1:=T\cdot P$$



$$Ry:=\begin{pmatrix} 0.7 & 0 & 0.7 & 0 \\ 0 & 1 & 0 & 0 \\ -0.7 & 0 & 0.7 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

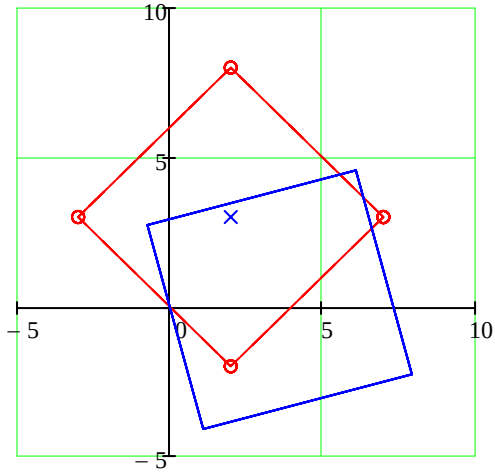
$$\left[\left(p^T\right)^{\langle 0\rangle},\left(p^T\right)^{\langle 1\rangle},\left(p^T\right)^{\langle 2\rangle}\right]$$

$$P0:=\begin{pmatrix} 5.5 \\ 6.5 \\ 5 \\ 1 \end{pmatrix} \qquad p:=T\cdot Ry\cdot T1\cdot P0$$

$$p=\begin{pmatrix} 7.95 \\ 6.5 \\ 1.05 \\ 1 \end{pmatrix}$$

Mirror Transformation :

$$\theta := 30\text{deg} \quad p := \text{Rz}(\theta) \cdot \text{Mirr} \cdot \text{Rz}(-\theta) \cdot P$$



$$x_c := 2 \quad y_c := 3$$

Perspective Transformation :

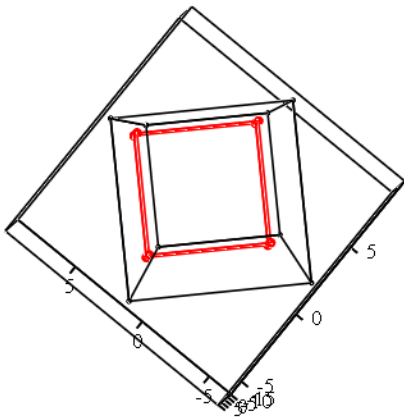
$$d_x := 0 \quad d_y := 0 \quad d_z := -15 \quad j := 0 \dots \text{cols}(P) - 1$$

$$T_p := \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & \frac{1}{d_z} & 0 \end{pmatrix} \quad T1 := \begin{pmatrix} 1 & 0 & 0 & -x_c \\ 0 & 1 & 0 & -y_c \\ 0 & 0 & 1 & d_z \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad T := \begin{pmatrix} 1 & 0 & 0 & x_c \\ 0 & 1 & 0 & y_c \\ 0 & 0 & 1 & -d_z \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$p := T_p \cdot T1 \cdot P \quad p_{x_j} := \frac{\frac{\left[\begin{pmatrix} p^T \end{pmatrix}^{(0)} \right]_j}{\left[\begin{pmatrix} p^T \end{pmatrix}^{(2)} \right]_j}}{d_z} \quad p_{y_j} := \frac{\frac{\left[\begin{pmatrix} p^T \end{pmatrix}^{(1)} \right]_j}{\left[\begin{pmatrix} p^T \end{pmatrix}^{(2)} \right]_j}}{d_z} \quad p_{z_j} := \frac{\frac{\left[\begin{pmatrix} p^T \end{pmatrix}^{(2)} \right]_j}{\left[\begin{pmatrix} p^T \end{pmatrix}^{(2)} \right]_j}}{d_z}$$

$$p_{0,j} := \left(p_x^T \right)_{0,j} \quad p_{1,j} := \left(p_y^T \right)_{0,j} \quad p := T \cdot p \quad p_{2,j} := \left[\begin{pmatrix} p^T \end{pmatrix}^{(2)} \right]_j$$

$$p_{2,j} := \left(p_z^T \right)_{0,j}$$



$$\left[\left(\mathbf{p}^T\right)^{\langle 0\rangle},\left(\mathbf{p}^T\right)^{\langle 1\rangle},\left(\mathbf{p}^T\right)^{\langle 2\rangle}\right],\left[\left(\mathbf{p}^T\right)^{\langle 0\rangle},\left(\mathbf{p}^T\right)^{\langle 1\rangle},\left(\mathbf{p}^T\right)^{\langle 2\rangle}\right]$$

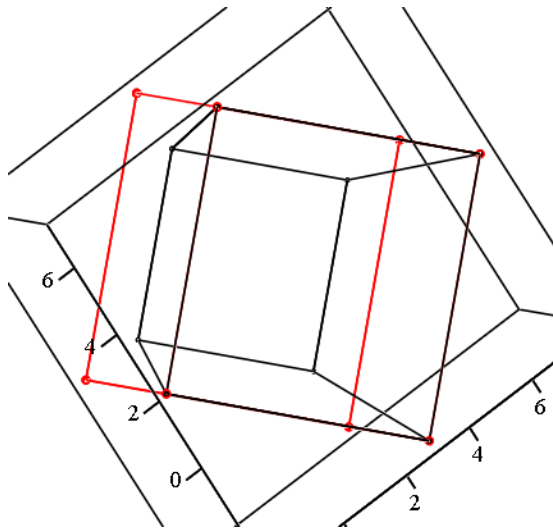
$$x_c:=2\qquad y_c:=3\qquad T:=\begin{pmatrix}1&0&0&x_c\\0&1&0&y_c\\0&0&1&0\\0&0&0&1\end{pmatrix}\qquad T1:=\begin{pmatrix}1&0&0&-x_c\\0&1&0&-y_c\\0&0&1&0\\0&0&0&1\end{pmatrix}$$

$$d_x:=0\qquad d_y:=0\qquad d_z:=10$$

$$p:=T1\cdot P\qquad p_{x_j}:=\frac{\frac{\left[\left(\mathbf{p}^T\right)^{\langle 0\rangle}\right]_j}{\left[\left(\mathbf{p}^T\right)^{\langle 2\rangle}\right]_j+1}}{d_z}+1\qquad p_{y_j}:=\frac{\frac{\left[\left(\mathbf{p}^T\right)^{\langle 1\rangle}\right]_j}{\left[\left(\mathbf{p}^T\right)^{\langle 2\rangle}\right]_j+1}}{d_z}+1$$

$$p_{0,j}:=\left(\mathbf{p}_x^T\right)_{0,j}$$

$$p_{1,j}:=\left(\mathbf{p}_y^T\right)_{0,j}\qquad p:=T\cdot p$$



$$\left[\left(p^T \right)^{\langle 0 \rangle}, \left(p^T \right)^{\langle 1 \rangle}, \left(p^T \right)^{\langle 2 \rangle} \right], \left[\left(p^T \right)^{\langle 0 \rangle}, \left(p^T \right)^{\langle 1 \rangle}, \left(p^T \right)^{\langle 2 \rangle} \right]$$

$$x' = x \cdot \cos(\theta) - y \cdot \sin(\theta)$$

$$\begin{pmatrix} x' & y' \end{pmatrix} = \begin{pmatrix} x & y \end{pmatrix} \cdot \begin{pmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{pmatrix}$$

$$y' = x \cdot \sin(\theta) + y \cdot \cos(\theta)$$

Plotting and Transforming a Triangle in 2D

$$Rz(\theta) := \begin{pmatrix} \cos(\theta) & \sin(\theta) & 0 \\ -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad T := \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix} \quad T1 := \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{pmatrix} \quad P := \begin{pmatrix} 2 & 5 & 3 & 2 \\ 3 & 6 & 8 & 3 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$\theta := 40\text{deg}$$

$$p := T \cdot Rz(\theta) \cdot T1 \cdot P$$

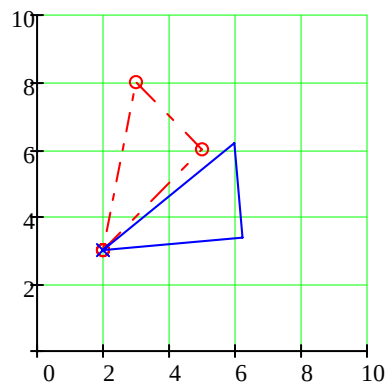
$$p := T \cdot Rz(\theta) \cdot T1 \cdot P$$

$$p = \begin{pmatrix} 2 & 6.226 & 5.98 & 2 \\ 3 & 3.37 & 6.187 & 3 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$\theta := -30\text{deg}$$

$$p := T1 \cdot P$$

$$p = \begin{pmatrix} 0 & 3 & 1 & 0 \\ 0 & 3 & 5 & 0 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$



Scaling a Triangle

$$P := \begin{pmatrix} 2 & 5 & 3 & 2 \\ 3 & 6 & 8 & 3 \\ 1 & 1 & 1 & 1 \end{pmatrix} \quad T := \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix} \quad T1 := \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{matrix} Sx := 2 \\ Sy := 2 \end{matrix}$$

$$S := \begin{pmatrix} Sx & 0 & 0 \\ 0 & Sy & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad p := T \cdot S \cdot T1 \cdot P$$

