

3D Mirror Transformation :

$$P = a + u \cdot b + v \cdot c$$

1. Plane Drawing :

$$m := 2 \quad i := 0..m \quad u_i := \frac{i}{m} \quad n := 2 \quad j := 0..n \quad v_j := \frac{j}{n}$$

$$P_0 := \begin{pmatrix} 2 \\ 0 \\ 9 \end{pmatrix} \quad P_1 := \begin{pmatrix} 1 \\ 10 \\ 5 \end{pmatrix} \quad P_2 := \begin{pmatrix} 8 \\ 6 \\ 10 \end{pmatrix} \quad n := \frac{(P_1 - P_0) \times (P_2 - P_0)}{|(P_1 - P_0) \times (P_2 - P_0)|} \quad n = \begin{pmatrix} 0.437 \\ -0.296 \\ -0.849 \end{pmatrix} \quad ns := n$$

$$P_2 := P_0 + n \times (P_1 - P_0) \quad P_3 := P_2 + (P_1 - P_0)$$

$$P_{i,j} := P_0 + u_i \cdot (P_1 - P_0) + v_j \cdot (P_2 - P_0) \quad x_{i,j} := (P_{i,j})_0 \quad y_{i,j} := (P_{i,j})_1 \quad z_{i,j} := (P_{i,j})_2$$

2. 3D Part Drawing :

$$pr := \begin{pmatrix} 7 & 2 & -3 & 2 & 7 & 2 & 2 & -3 & 2 & 2 \\ 3 & 8 & 3 & -2 & 3 & 3 & 8 & 3 & 3 & -2 \\ 0 & 0 & 0 & 0 & 0 & 5 & 0 & 0 & 5 & 0 \end{pmatrix}$$

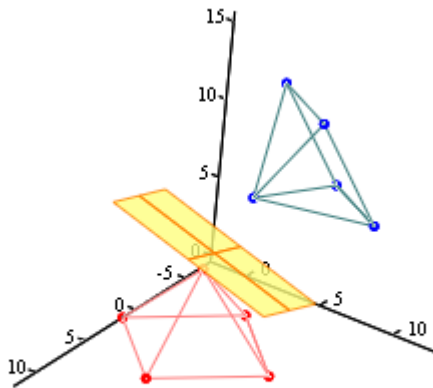
$$i := 0..cols(pr) - 1$$

$$j := 0..rows(pr) - 2$$

$$prs_{j,i} := pr_{j,i}$$

3. Mirror of part with respect to plane :

$$p^{(i)} := pr^{(i)} + 2 \cdot n \cdot [(P_0 - pr^{(i)}) \cdot n]$$



$$[(pr^T)^{(0)}, (pr^T)^{(1)}, (pr^T)^{(2)}], [(p^T)^{(0)}, (p^T)^{(1)}, (p^T)^{(2)}], (x, y, z)$$

3. 3D Mirror by using mirror transformation matrix :

$$\theta_x := \operatorname{atan}\left[\frac{n_1}{\sqrt{(n_0)^2 + (n_2)^2}}\right] \quad \theta_x = -17.213\text{deg} \quad \theta_y := \operatorname{atan}\left(\frac{n_0}{n_2}\right) \quad \theta_y = -27.255\text{deg}$$

$$\text{Mirr} := \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \text{Rx}(\theta) := \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(\theta) & -\sin(\theta) & 0 \\ 0 & \sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \text{Rz}(\theta) := \begin{pmatrix} \cos(\theta) & -\sin(\theta) & 0 & 0 \\ \sin(\theta) & \cos(\theta) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

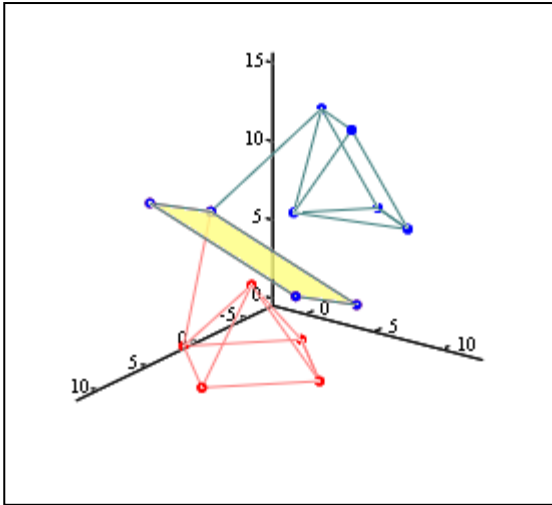
$$\text{T} := \begin{pmatrix} 1 & 0 & 0 & P_{00} \\ 0 & 1 & 0 & P_{01} \\ 0 & 0 & 1 & P_{02} \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \text{T1} := \begin{pmatrix} 1 & 0 & 0 & -P_{00} \\ 0 & 1 & 0 & -P_{01} \\ 0 & 0 & 1 & -P_{02} \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \text{Ry}(\theta) := \begin{pmatrix} \cos(\theta) & 0 & \sin(\theta) & 0 \\ 0 & 1 & 0 & 0 \\ -\sin(\theta) & 0 & \cos(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$n := \frac{P_1 - P_0}{|P_1 - P_0|} \quad n = \begin{pmatrix} -0.092 \\ 0.925 \\ -0.37 \end{pmatrix} \quad \begin{pmatrix} n_x \\ n_y \\ n_z \end{pmatrix} := n \quad |n| = 1$$

$$\text{pr} := \begin{pmatrix} 7 & 2 & -3 & 2 & 7 & 2 & 2 & -3 & 2 & 2 & P_{00} & P_{10} & P_{30} & P_{20} & P_{00} \\ 3 & 8 & 3 & -2 & 3 & 3 & 8 & 3 & 3 & -2 & P_{01} & P_{11} & P_{31} & P_{21} & P_{01} \\ 0 & 0 & 0 & 0 & 0 & 5 & 0 & 0 & 5 & 0 & P_{02} & P_{12} & P_{32} & P_{22} & P_{02} \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{pmatrix}$$

$$\text{R}(\theta) := \begin{bmatrix} n_x^2 \cdot (1 - c(\theta)) + c(\theta) & n_x \cdot n_y \cdot (1 - c(\theta)) - n_z \cdot s(\theta) & n_x \cdot n_z \cdot (1 - c(\theta)) + n_y \cdot s(\theta) & 0 \\ n_x \cdot n_y \cdot (1 - c(\theta)) + n_z \cdot s(\theta) & n_y^2 \cdot (1 - c(\theta)) + c(\theta) & n_y \cdot n_z \cdot (1 - c(\theta)) - n_x \cdot s(\theta) & 0 \\ n_x \cdot n_z \cdot (1 - c(\theta)) - n_y \cdot s(\theta) & n_y \cdot n_z \cdot (1 - c(\theta)) - n_x \cdot s(\theta) & n_z^2 \cdot (1 - c(\theta)) + c(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\text{R}\left(\frac{\pi}{3}\right) = \begin{pmatrix} 0.504 & 0.278 & 0.818 & 0 \\ -0.363 & 0.927 & -0.091 & 0 \\ -0.784 & -0.091 & 0.568 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad p := \text{T} \cdot (\text{Ry}(\theta_y) \cdot \text{Rx}(\theta_x)) \cdot \text{Mirr} \cdot \text{Rx}(-\theta_x) \cdot \text{Ry}(-\theta_y) \cdot \text{T1} \cdot \text{pr}$$



$$\left[\left(p^T\right)^{\langle 0\rangle},\left(p^T\right)^{\langle 1\rangle},\left(p^T\right)^{\langle 2\rangle}\right],\left[\left(p^T\right)^{\langle 0\rangle},\left(p^T\right)^{\langle 1\rangle},\left(p^T\right)^{\langle 2\rangle}\right],(x, y, z)$$