FIZ101E – Lecture 3 Newton's laws of motion

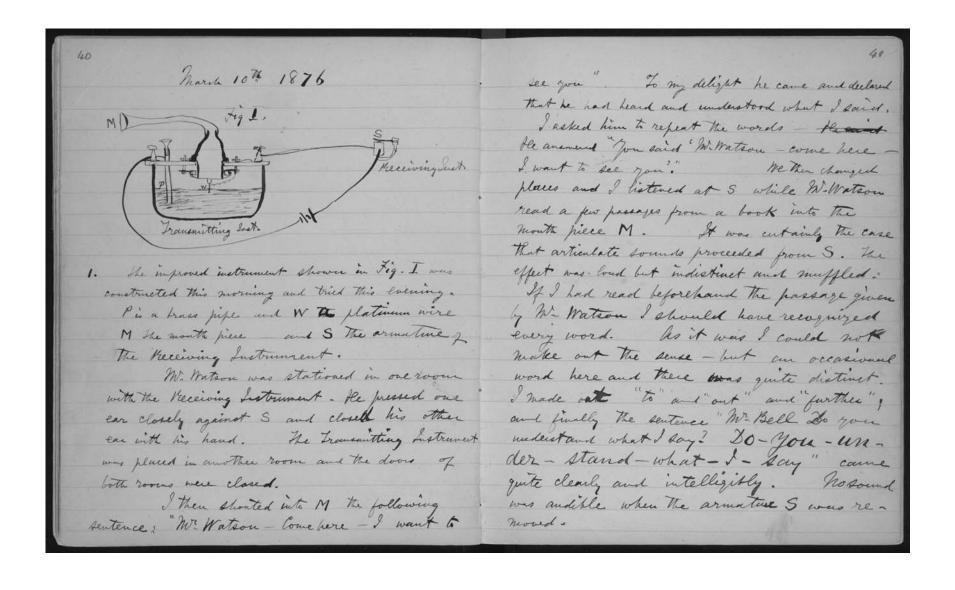


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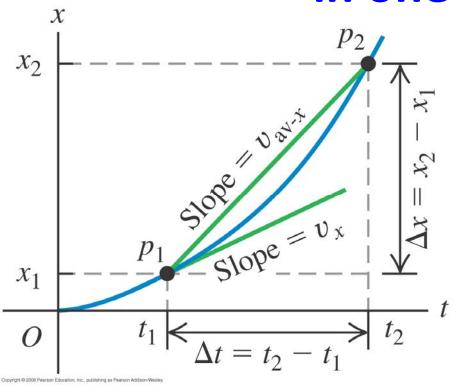
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What did we cover last week?



Average and instantaneous velocity in one dimension



At time t_1 , particle is located at x_1 , at time t_2 , it is located at x_2



Particle <u>displacement</u> $\Delta x = x_2 - x_1$

Average velocity of the particle in the time interval $\Delta t = t_2 - t_1$

$$v_{av-x} = \frac{x_2 - x_1}{t_2 - t_1} = \frac{\Delta x}{\Delta t}$$

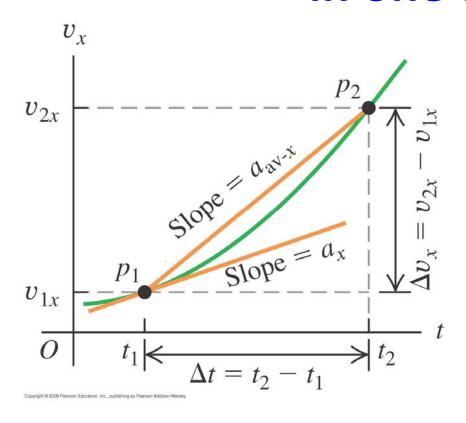
<u>Instantaneous velocity</u> of the particle at any time *t*

$$v_x = \lim_{\Delta t \to 0} v_{av-x} = \lim_{\Delta t \to 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$$



<u>Derivative</u> of the particle position with respect to time

Average and instantaneous acceleration in one dimension



At time t_1 , particle has a velocity v_{1x} , at time t_2 , it has a velocity v_{2x}



Change of particle velocity $\Delta v_x = v_{2x} - v_{1x}$

Average acceleration of the particle in the time interval $\Delta t = t_2 - t_1$

$$a_{av-x} = \frac{v_{2x} - v_{1x}}{t_2 - t_1} = \frac{\Delta v_x}{\Delta t}$$

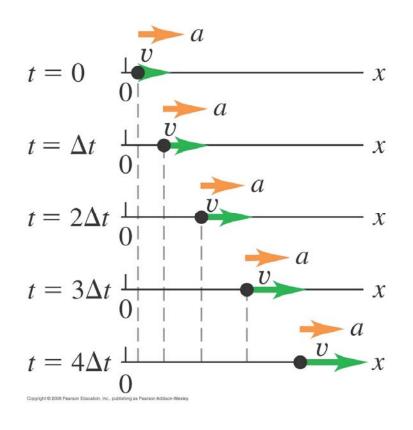
Instantaneous acceleration of the particle at any time *t*

$$a_{x} = \lim_{\Delta t \to 0} a_{av-x} = \lim_{\Delta t \to 0} \frac{\Delta v_{x}}{\Delta t} = \frac{dv_{x}}{dt}$$



<u>Derivative</u> of the particle velocity with respect to time

Straight-line motion with constant acceleration



With constant acceleration a_x , particle velocity changes <u>linearly</u> with time:

$$\left|v_{x}=v_{0x}+a_{x}t\right|$$

With constant acceleration a_x , particle position changes <u>quadratically</u> with time:

$$x = x_0 + v_{0x}t + \frac{1}{2}a_xt^2$$

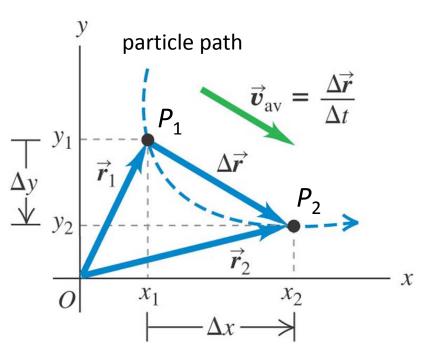
Eliminating time from velocity and position equations, we can also write:

$$v_x^2 = v_{0x}^2 + 2a_x(x - x_0)$$



Only valid for constant acceleration motion!!!

Position and velocity vectors



Position vector $\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$

- Points from the origin O to point P
- Components are x, y, z coordinates

Displacement vector

$$\Delta \vec{r} = \vec{r}_2 - \vec{r}_1$$

Characterizes motion from P_1 to P_2

Average velocity of the particle in a time interval $\Delta t = t_2 - t_1$

$$\vec{v}_{av} = \frac{\vec{r}_2 - \vec{r}_1}{t_2 - t_1} = \frac{\Delta \vec{r}}{\Delta t}$$

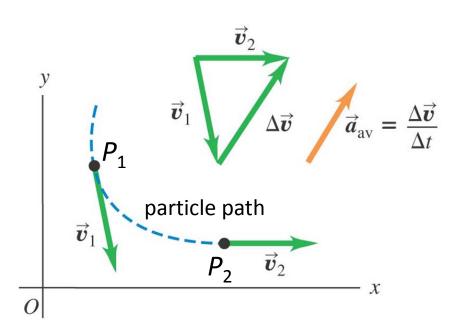
<u>Instantaneous velocity</u> of the particle at any time *t*

$$\vec{v} = \lim_{\Delta t \to 0} \vec{v}_{av} = \lim_{\Delta t \to 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d\vec{r}}{dt}$$
$$= \left(\frac{dx}{dt}\right) \hat{i} + \left(\frac{dy}{dt}\right) \hat{j} + \left(\frac{dz}{dt}\right) \hat{k}$$



<u>Derivative</u> of the particle position vector with respect to time

Acceleration vector



Velocity vector is always <u>tangent</u> to the particle path

During motion from P_1 to P_2 , both magnitude and direction of velocity can change:

$$\Delta \vec{v} = \vec{v}_2 - \vec{v}_1$$

Average acceleration of the particle in a time interval $\Delta t = t_2 - t_1$

$$\vec{a}_{av} = \frac{\vec{v}_2 - \vec{v}_1}{t_2 - t_1} = \frac{\Delta \vec{v}}{\Delta t}$$

<u>Instantaneous acceleration</u> of the particle at any time *t*

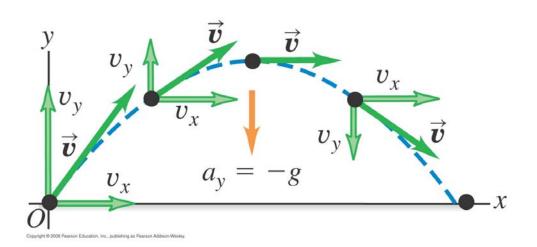
$$|\vec{a}| = \lim_{\Delta t \to 0} \vec{a}_{av} = \lim_{\Delta t \to 0} \frac{\Delta \vec{v}}{\Delta t} = \frac{d\vec{v}}{dt}$$

$$= \left(\frac{dv_x}{dt}\right) \hat{i} + \left(\frac{dv_y}{dt}\right) \hat{j} + \left(\frac{dv_z}{dt}\right) \hat{k}$$



<u>Derivative</u> of the particle velocity vector with respect to time

Projectile motion



Idealized projectile

= particle given an initial velocity whose movement is then influenced only by the (constant) acceleration of gravity, with no air resistance

Position and velocity of the projectile are described by:

$$x = v_{0x}t$$

$$v_x = v_{0x}$$



Constant velocity motion in the horizontal x-direction

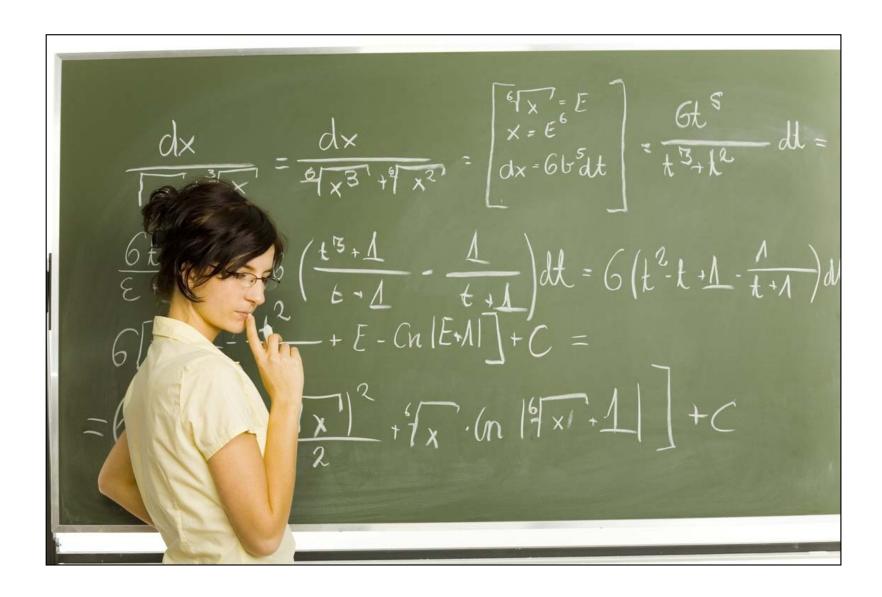
$$y = v_{0y}t - \frac{1}{2}gt^2$$

$$v_{y} = v_{0y} - gt$$



Constant acceleration motion in the vertical y-direction

What will we cover today?



Lesson plan

- 1. Force and interactions
- 2. Newton's First Law
- 3. Newton's Second Law
- 4. Mass and weight
- 5. Newton's Third Law
- 6. Free-body diagrams