

Istanbul Technical University Faculty of Mechanical Engineering  
**MAK422E Engineering Design and CAD** Midterm Exam,  
Nov.05, 2013, Instructor: Hikmet Kocabas Time: 90 minutes

**1. (10) Write down the output devices in CAD.**

Printers (pin, inkjet, laser), Plotter (pen, inkjet), 3D printer (STL),  
CNC, Display screens (tube, vector, raster, CRT, flat panel, LCD,  
LED, TFT, plasma), Touch screen (OLED, flexible amoled, FOLED),  
e-ink, mirasol, projector, stereo 3D LED, stereo Eyeglasses, 3D  
holograms, Google glass.

Detailed list:

Output Devices

Printers, Plotters (Hardcopy Technologies):

Typewriter, ballhead, dotmatrix, pin printer (impact technology),  
(electrostatic, thermal technology) inkjet printer, inkjet plotter,  
pen plotter (flatbed, drum, grit drive, pinfeed),  
laser printer, laser plotter,  
3D printing, stereolithography (STL),

Displays (Display Technology):

Direct View Storage Tube (DVST),  
Vector Refresh Display, Storage Tube,  
Mono-chrome/Color Refresh Cathode Ray Tube (CRT),

Raster Scan Display, Color Raster Display,  
Gas Plasma display,  
Liquid crystal display (LCD),  
Light emitting diode (LED) display, Electro-luminescent display,  
Organic light emitting diode (OLED)  
Flexible Organic light emitting diode (FOLED)  
Flexible amoled panels  
Touch Screen Display  
e-book, e-ink microcapsule  
mirasol display

3D tv technology, polarized light system, passive/active shutter  
system, lenticular system, parallax-barrier system

Holograms

Projectors

## 2. (10) What are some of properties of Bezier blending functions?

Properties of the Bezier blending functions  $B_i^n(u)$ :

Blending functions  $B_i^n(u)$  are all polynomials of order (degree)  $n$

where  $n+1$  is the number of control points

the range of  $u$  is  $0 \leq u \leq 1$

Blending functions sum to one (partition of unity)

All functions are non-negative (positivity),  $B_i^n(u) \geq 0$

Continuity:  $B_i^n(u)$  is  $(n-2)$  times continuously differentiable

Global control: Moving the Control points effect the whole curve. The Blending functions of the first and last points (end points) have value 1 at their own parameters

The polynomials can be computed by the recursive relation

The blending polynomials are symmetric

$$B_i^n(u)$$

$$0 \leq u \leq 1$$

$$\sum_{i=0}^n B_i^n(u) = 1$$

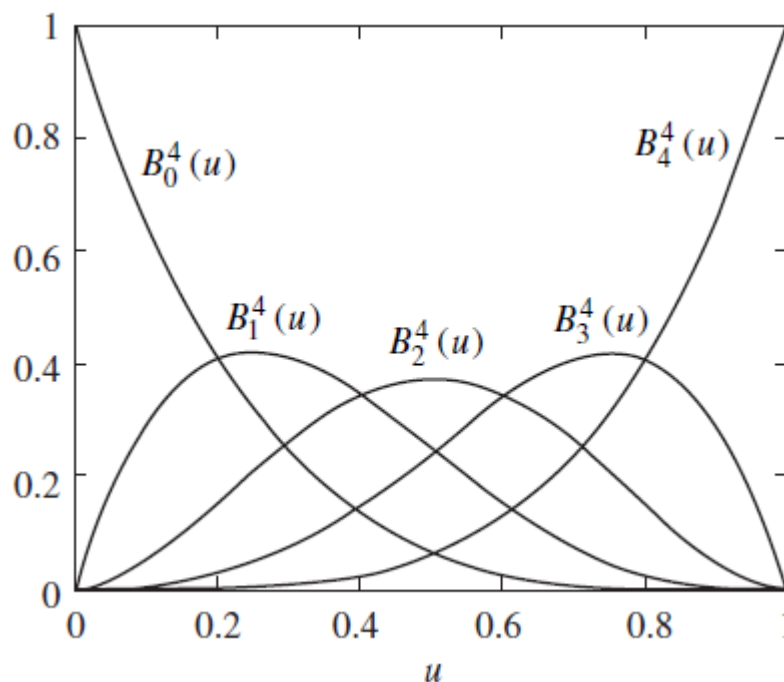
$$\sum_{i=0}^n B(i, n, u) = 1$$

$$\text{Bezier curve } p(u) = \sum_{i=0}^n \left[ (P^{(0)})_i \cdot B(i, n, u) \right]$$

$$\text{Binomial function } C(n, i) = \frac{n!}{i! \cdot (n-i)!}$$

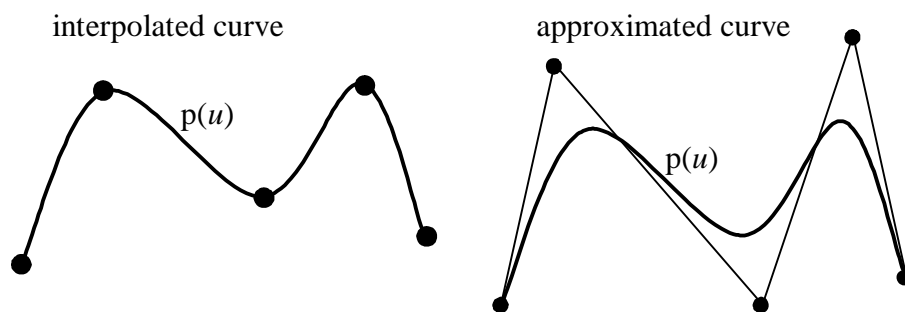
Bernstien Polynomials as blending functions  $B_i^n(u)$ :

$$B(i, n, u) = C(n, i) \cdot u^i \cdot (1-u)^{n-i} \geq 0$$

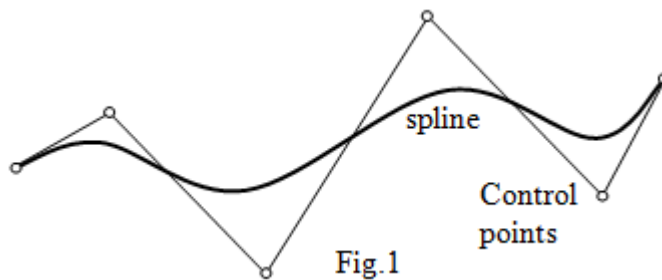


3. (10) What is the difference between interpolated and approximated curves?

A curve uses  $(P_1, P_2 \dots P_n)$  control points for approximate form, or points on curve for interpolate form. Curve degree is  $(n-1)$ , where  $n$  is the number of points.

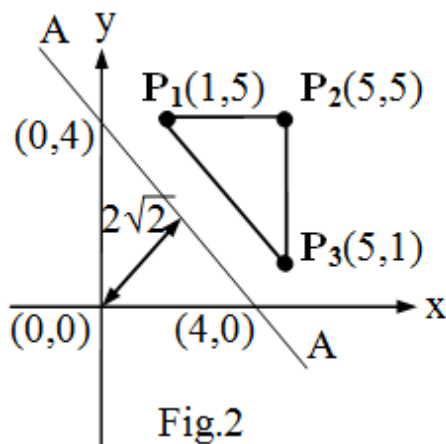


3. (10) What is the maximum degree of spline curve in Fig.1? Why?



where  
 number of control point :  $n$   
 $n = 6$   
 degree of spline :  $m$   
 $m = n - 1$   
 $m = 6 - 1 = 5$

4. (30) Mirror the given right triangle (Fig.2) around axis A-A, which is parallel to the hypotenuse. Use transformation matrix for solution.

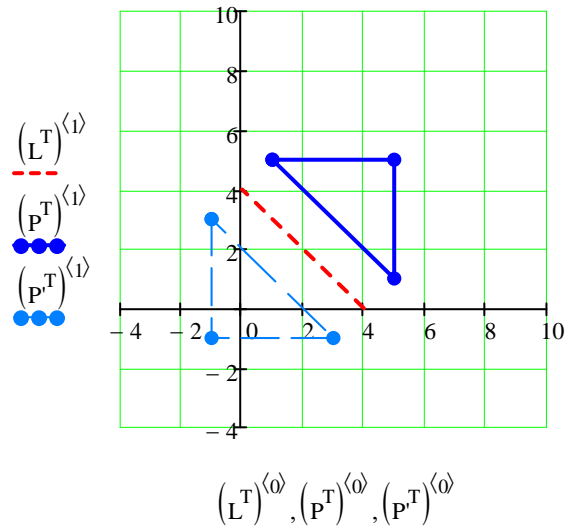


$$\alpha := 45\text{deg} \quad R_z(\alpha) := \begin{pmatrix} \cos(\alpha) & -\sin(\alpha) & 0 \\ \sin(\alpha) & \cos(\alpha) & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

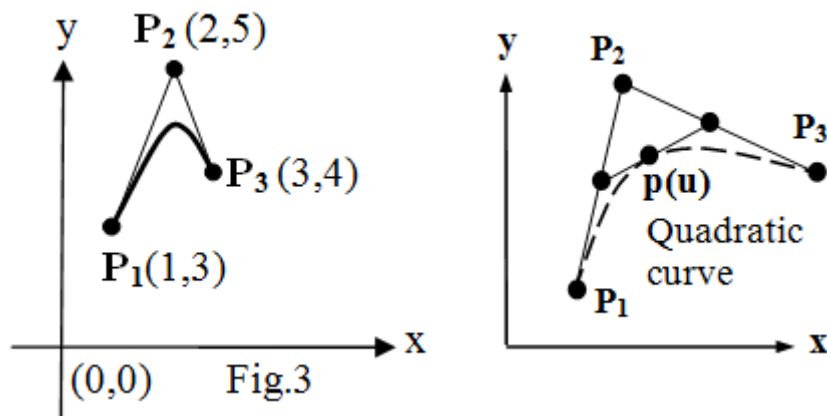
$$T_{\omega\omega} := \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad M_x := \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$L_{\omega\omega} := \begin{pmatrix} 4 & 0 \\ 0 & 4 \\ 1 & 1 \end{pmatrix} \quad P := \begin{pmatrix} 1 & 5 & 5 & 1 \\ 5 & 5 & 1 & 5 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$P' := T \cdot \text{Rz}(-\alpha) \cdot M_X \cdot \text{Rz}(\alpha) \cdot T^{-1} \cdot P \quad P' = \begin{pmatrix} -1 & -1 & 3 & -1 \\ 3 & -1 & -1 & 3 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$



**5. (30 points)** A Bezier curve  $p(u)$  is defined by control points in Fig.3. Use the iterative (recursive subdivision, linear interpolation, deCasteljau, DeBoor) algorithm to compute:  $p(1/2)$ .



$$P_1 := \begin{pmatrix} 1 \\ 3 \end{pmatrix} \quad P_2 := \begin{pmatrix} 2 \\ 5 \end{pmatrix} \quad P_3 := \begin{pmatrix} 3 \\ 4 \end{pmatrix} \quad P := \text{augment}(P_1, P_2, P_3)$$

$$p(u) := [P_1 + u \cdot (P_2 - P_1)] + u \cdot [P_2 + u \cdot (P_3 - P_2)] - [P_1 + u \cdot (P_2 - P_1)]$$

$$p(u) = (u^2 - 2 \cdot u + 1) \cdot P_1 + (2 \cdot u - 2 \cdot u^2) \cdot P_2 + u^2 \cdot P_3$$

$$p(u) = (1 - u)^2 \cdot P_1 + 2 \cdot u \cdot (1 - u) \cdot P_2 + u^2 \cdot P_3$$

$$p(u) \text{ simplify } \rightarrow \begin{pmatrix} 2 \cdot u + 1 \\ 4 \cdot u - 3 \cdot u^2 + 3 \end{pmatrix} \qquad p\left(\frac{1}{2}\right) = \begin{pmatrix} 2 \\ 4.25 \end{pmatrix}$$

$$i := 0..10 \qquad u_i := \frac{i}{10}$$

$$x(u) := 2 \cdot u + 1$$

$$y(u) := 4 \cdot u - 3 \cdot u^2 + 3 \qquad p\left(\frac{1}{2}\right)_0 = 2 \qquad p\left(\frac{1}{2}\right)_1 = 4.25$$

